

The Brain and the Modern AI

Drastic differences and curious similarities

Ilya Kuzovkin



UNIVERSITY
OF TARTU

OFFWORLD

A supercomputer that works like the human brain has just been turned on

Manchester University just switched on the world's largest neuromorphic supercomputer

Science News Technology Space NASA Artificial Intelligence Weird Science Science of Sci-Fi

MIT Scientists Design a Computer That Works Just Like a Human Brain

Technology Artificial Intelligence

Researchers developed algorithms that mimic the human brain (and the results don't suck)

IBM is teaching AI to behave more like the human brain

Soon machines will be able to pay atte

Intel Developing an AI Chip That Acts Like a Human Brain

INSIGHTS 🔍 ☰

Before you know it!

It won't be long before AI mimics a human brain to do more, with less – just like we can.

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MIT researchers develop new chip design to take us closer to computers that work like human brains

PUBLISHED MON, OCT 8 2018 · 8:26 AM EDT | UPDATED WED, OCT 10 2018 · 10:29 AM EDT

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Do neural networks really work like neurons?

Why Artificial Intelligence Is Not Like Your Brain—

Contrary to belief, artificial intelligence is not like a rocket scientist.

The Wrong Cognitive Measuring Stick

Why it's a mistake to compare A.I. with human intelligence

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Blog

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The empty brain

Your brain does not process information, retrieve knowledge or store memories. In short: your brain is not a computer

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How neuroscience enables better Artificial Intelligence design

How AI and neuroscience drive each other forwards

Experts

Three Invaluable Ways AI and Neuroscience Are Driving Each Other Forward

BLOG POST RESEARCH

Neuron

AI and Neuroscience: A virtuous circle

REVIEW | VOLUME

Neuroscience-Inspired Artificial Intelligence
Demis Hassabis • Dharshan Kumaran • Christopher Summerfield • Matthew Botvinick

convergence of neuroscience and artificial intelligence

Science

Neuroscience and artificial intelligence can help improve each other

July 9, 2019 9:23pm AEST

SHARE PERSPECTIVE NEUROSCIENCE



Using neuroscience to develop artificial intelligence

We need to **structure** this conversation



Suggestion

David Marr's

Three levels of analysis

We need to structure this conversation



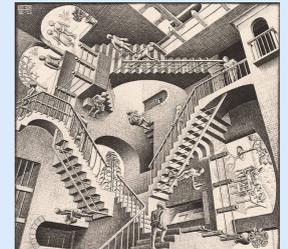
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Three levels of analysis

Goal of the computation

What is the purpose of computation?



We need to **structure** this conversation



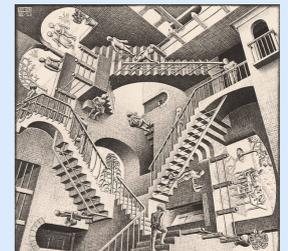
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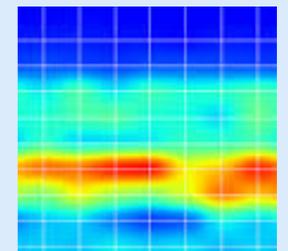
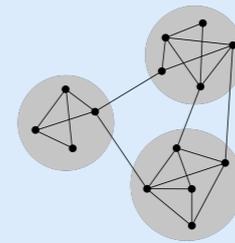
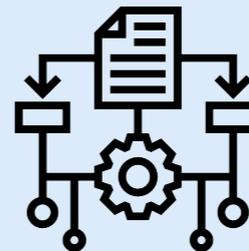
What is the purpose of computation?



Algorithm and representation

What representations does the system use?

What processes are in use to manipulate representations?



We need to structure this conversation



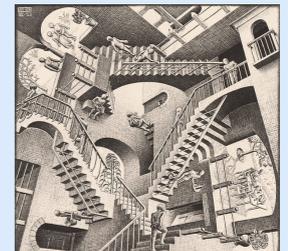
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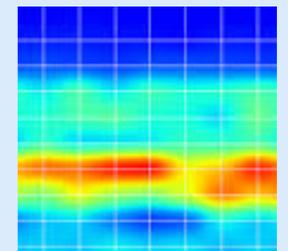
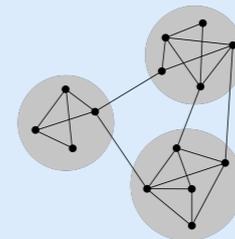
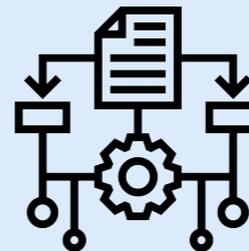
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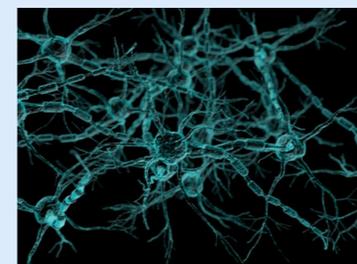
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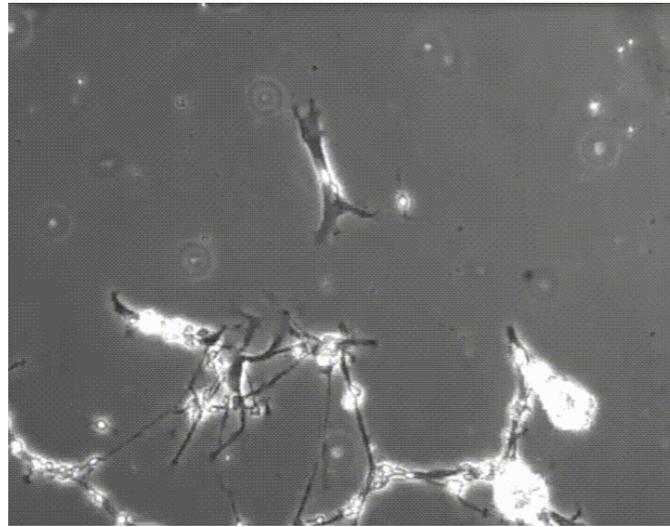
What processes are in use to manipulate representations?



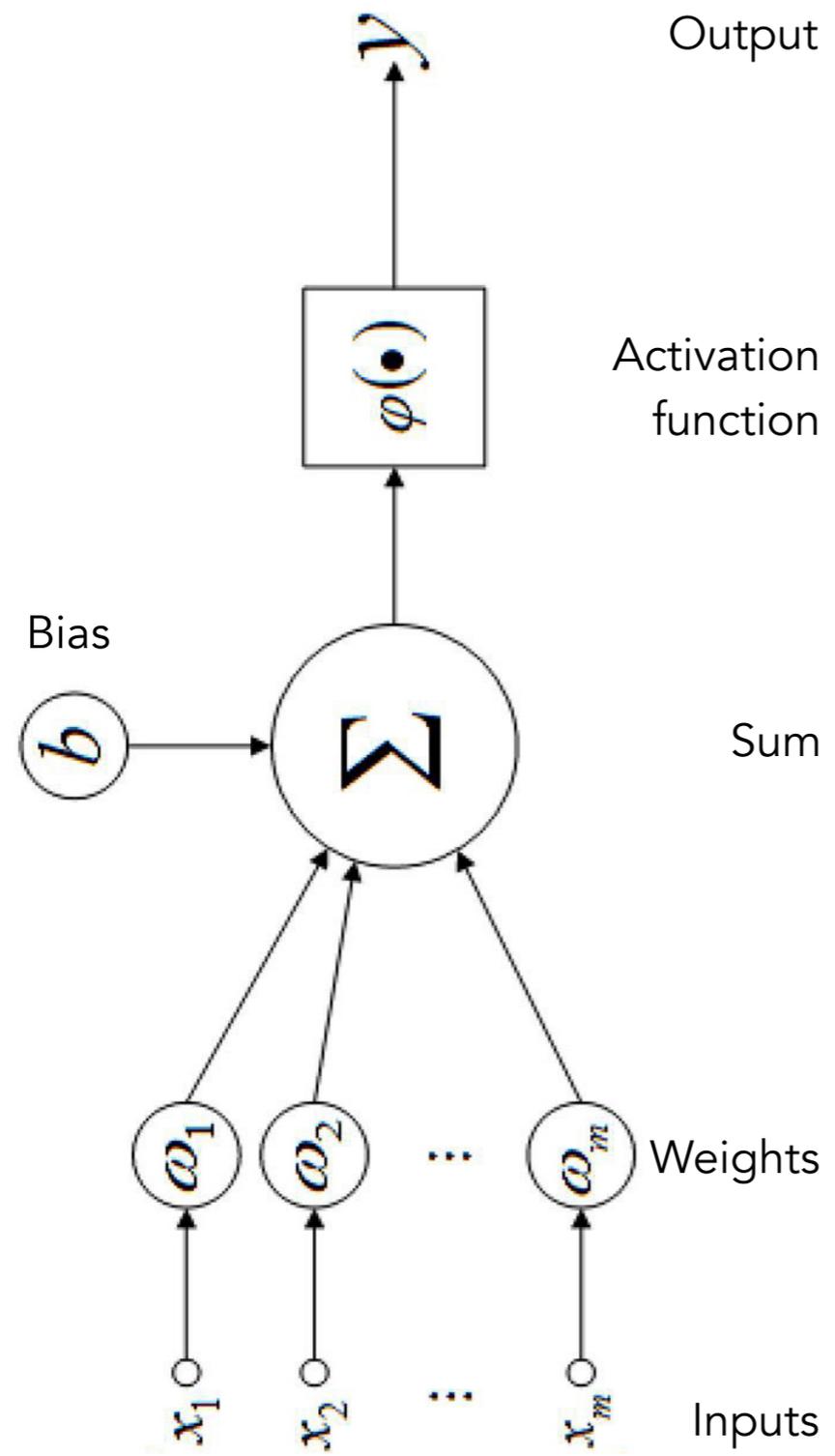
Implementation

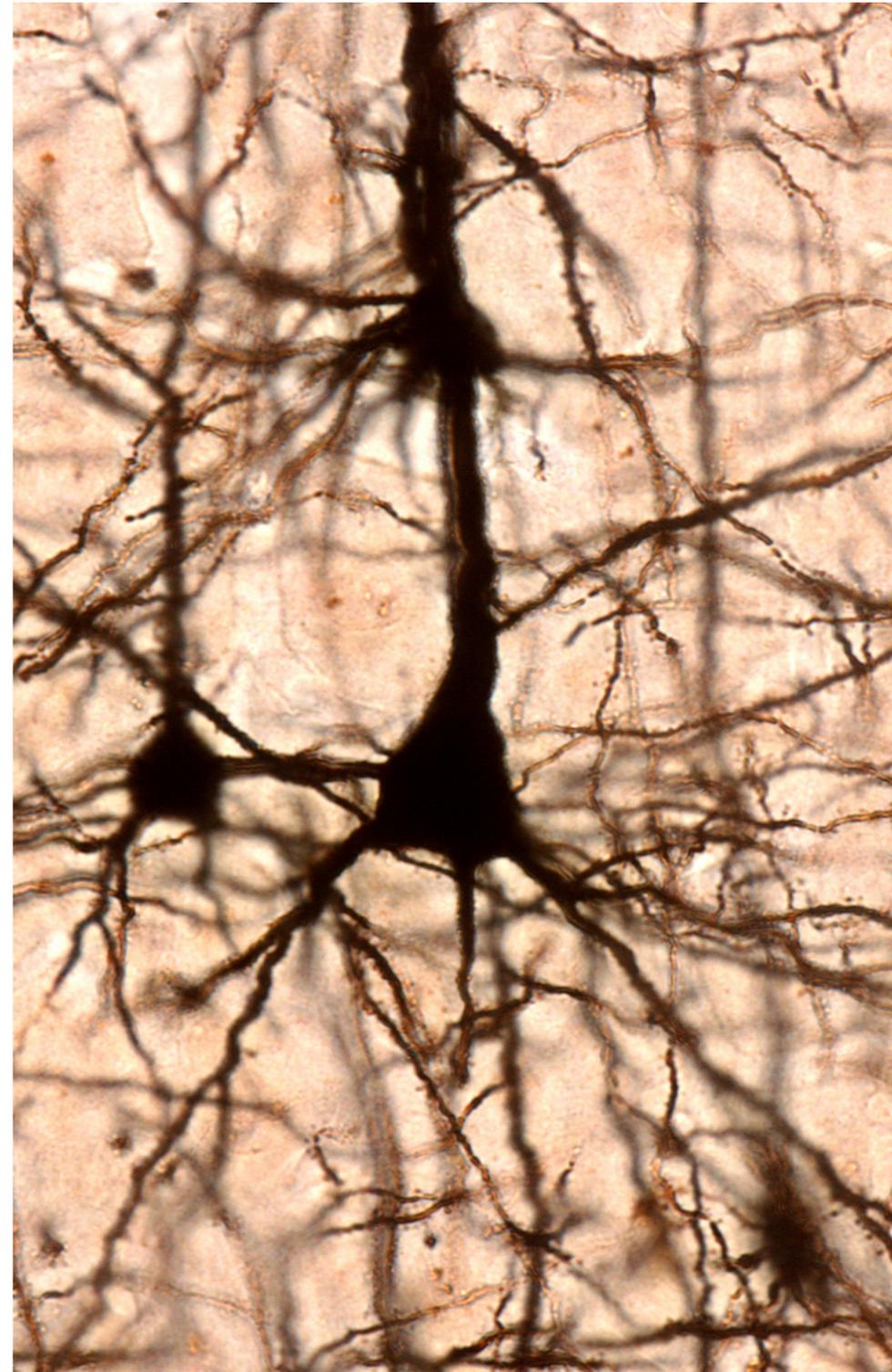
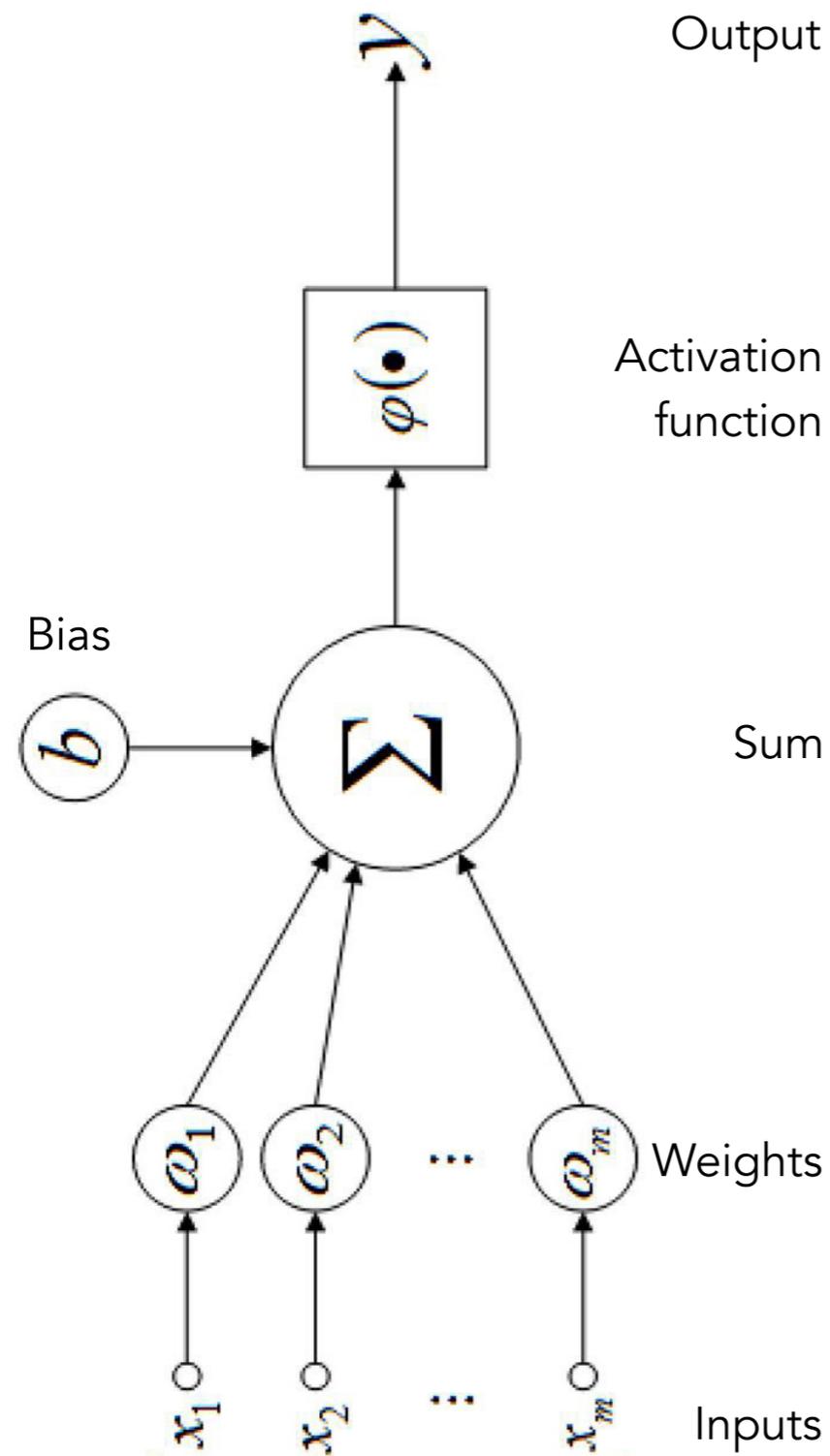
How is the system physically realized?

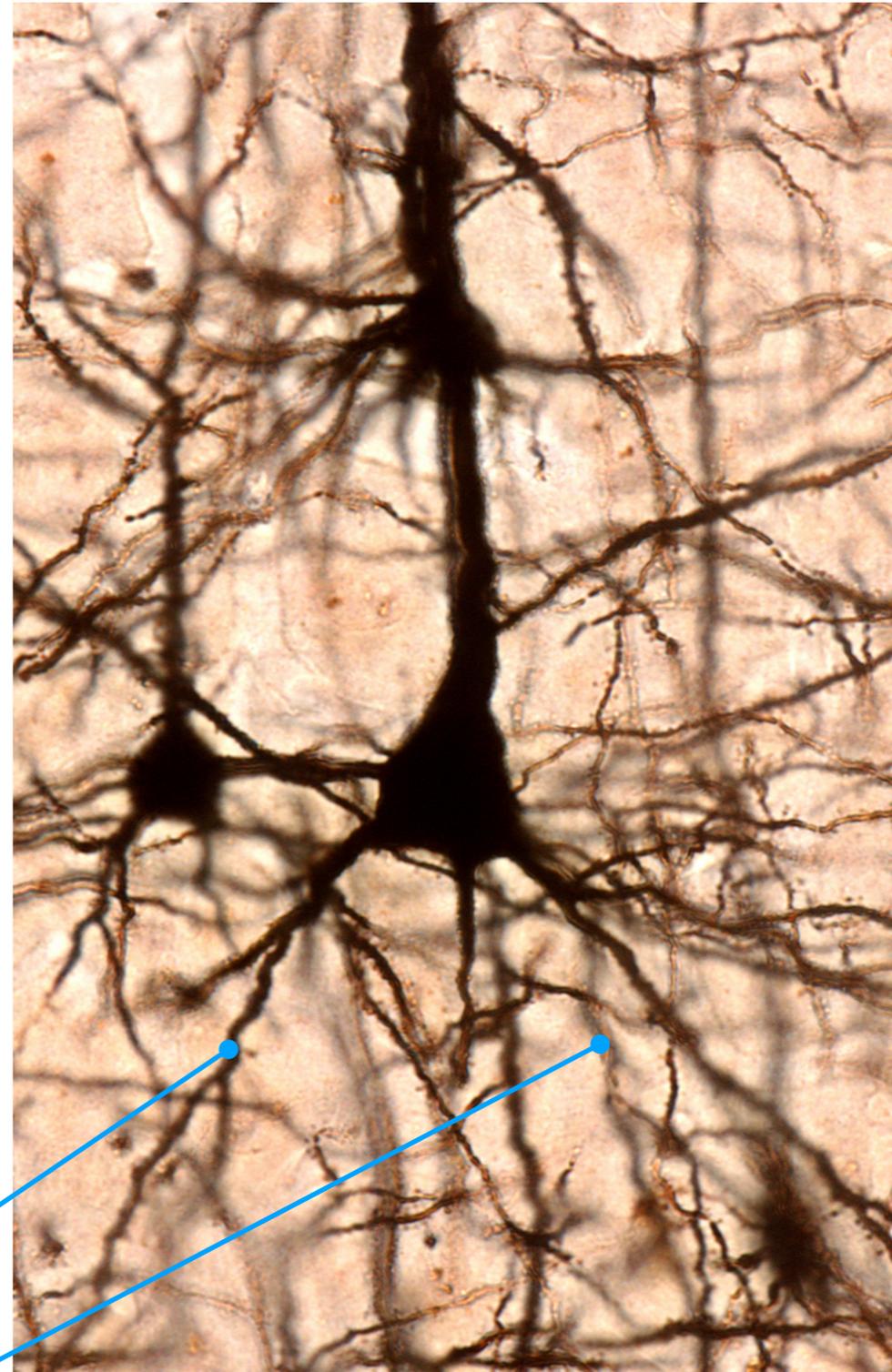
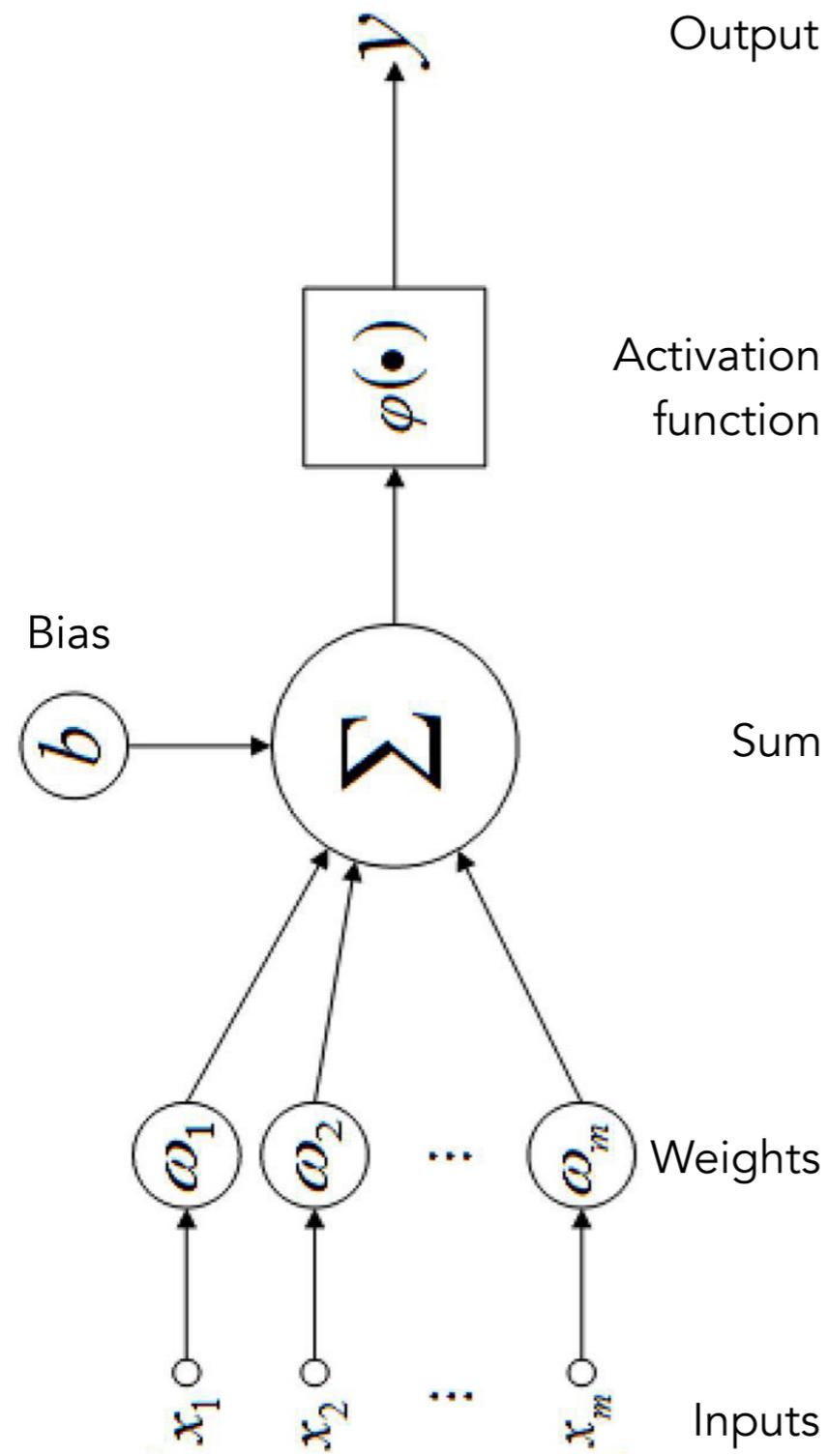




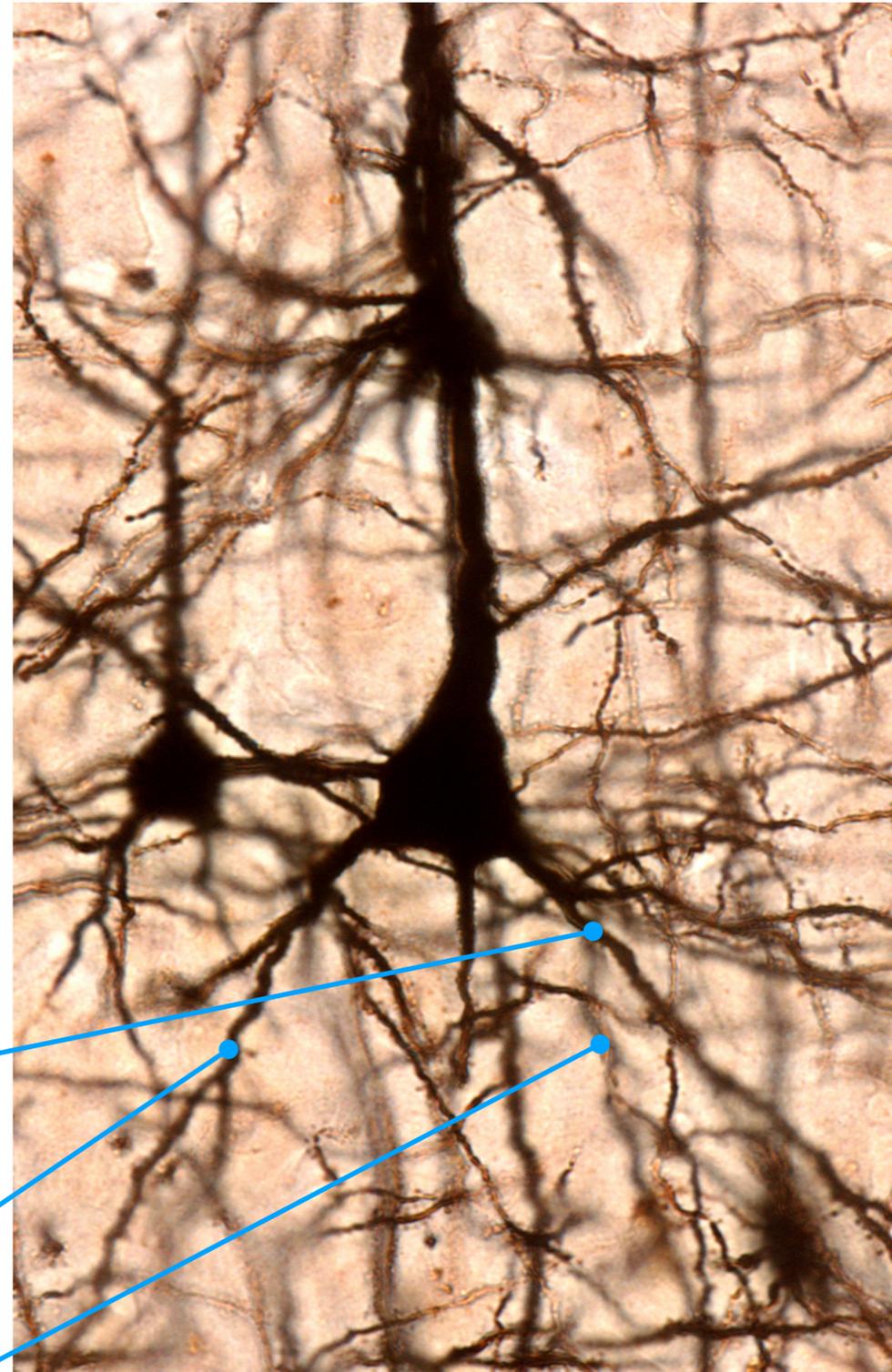
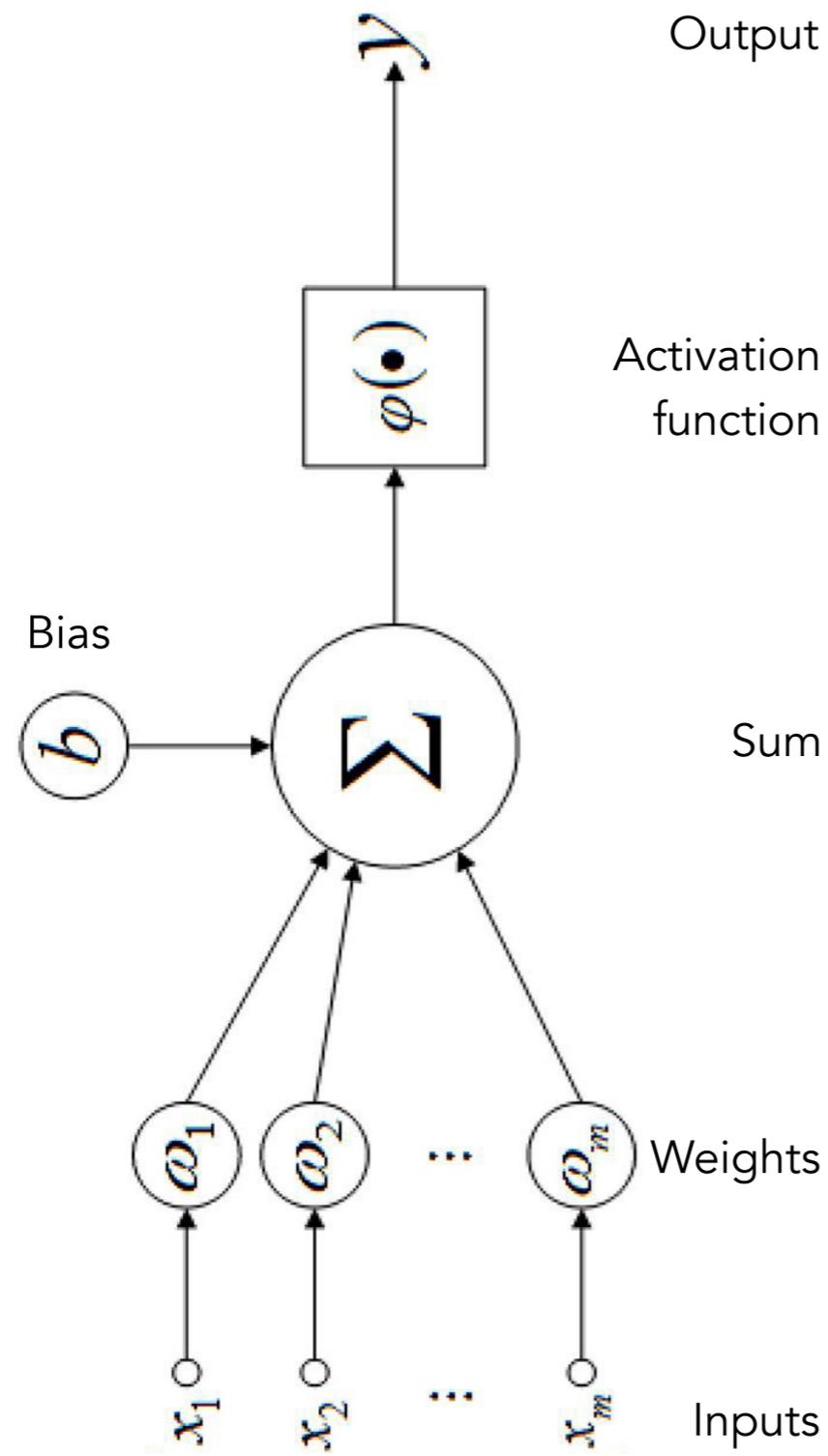
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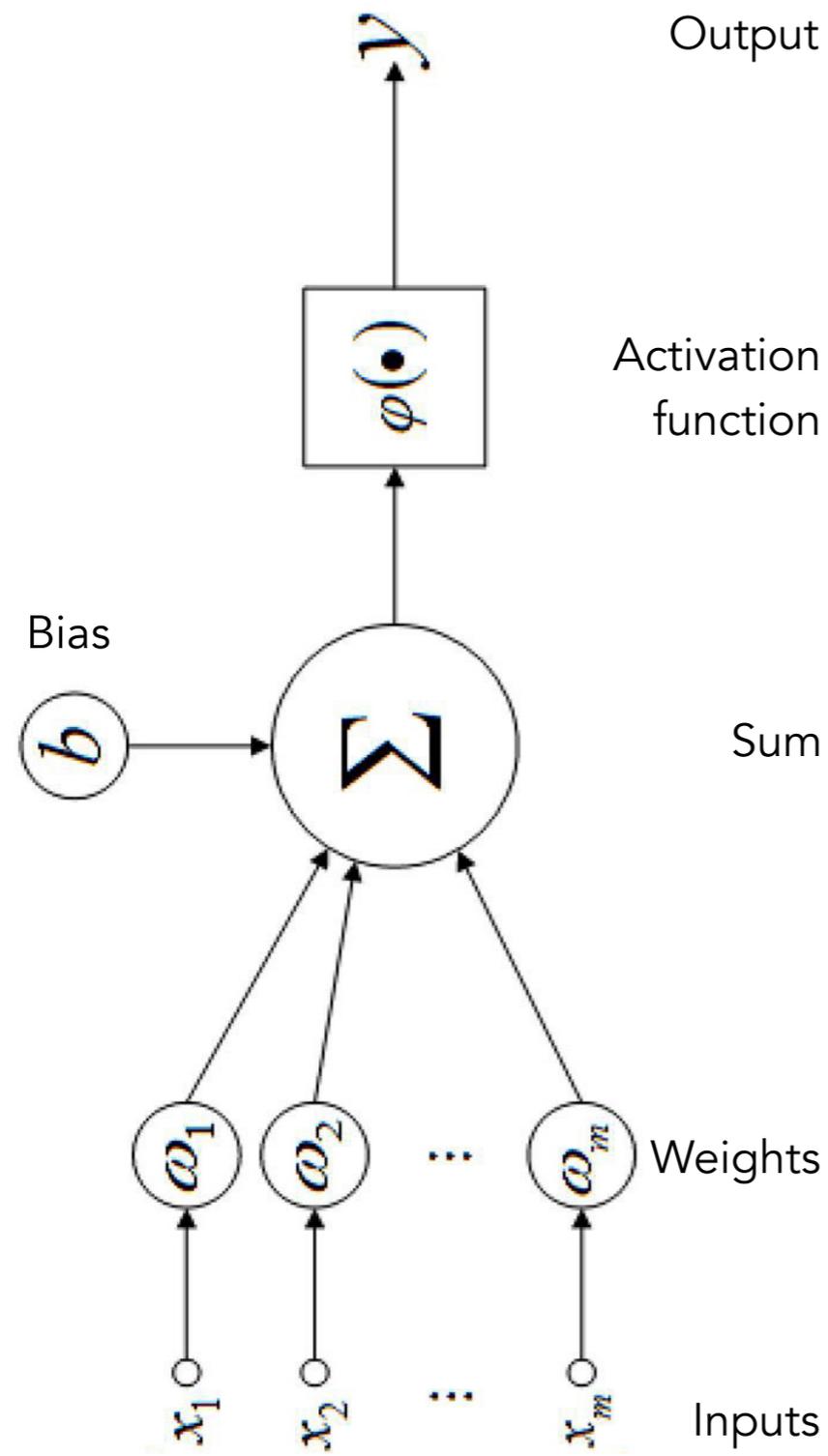




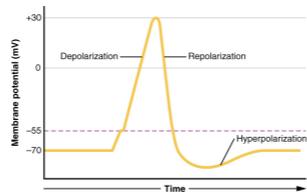


Dendrites
Axon terminals
(from other neurons)





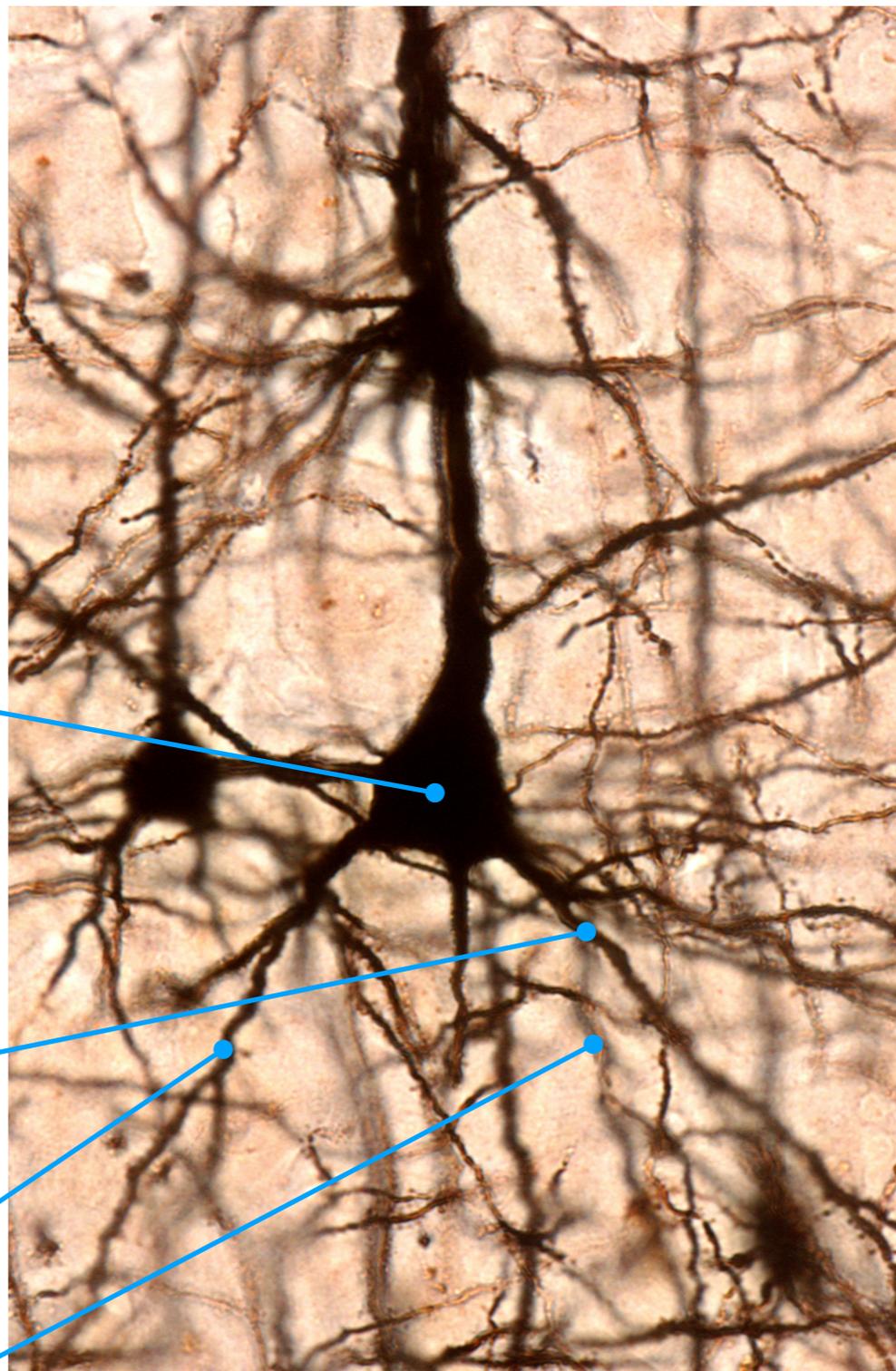
Cell depolarization

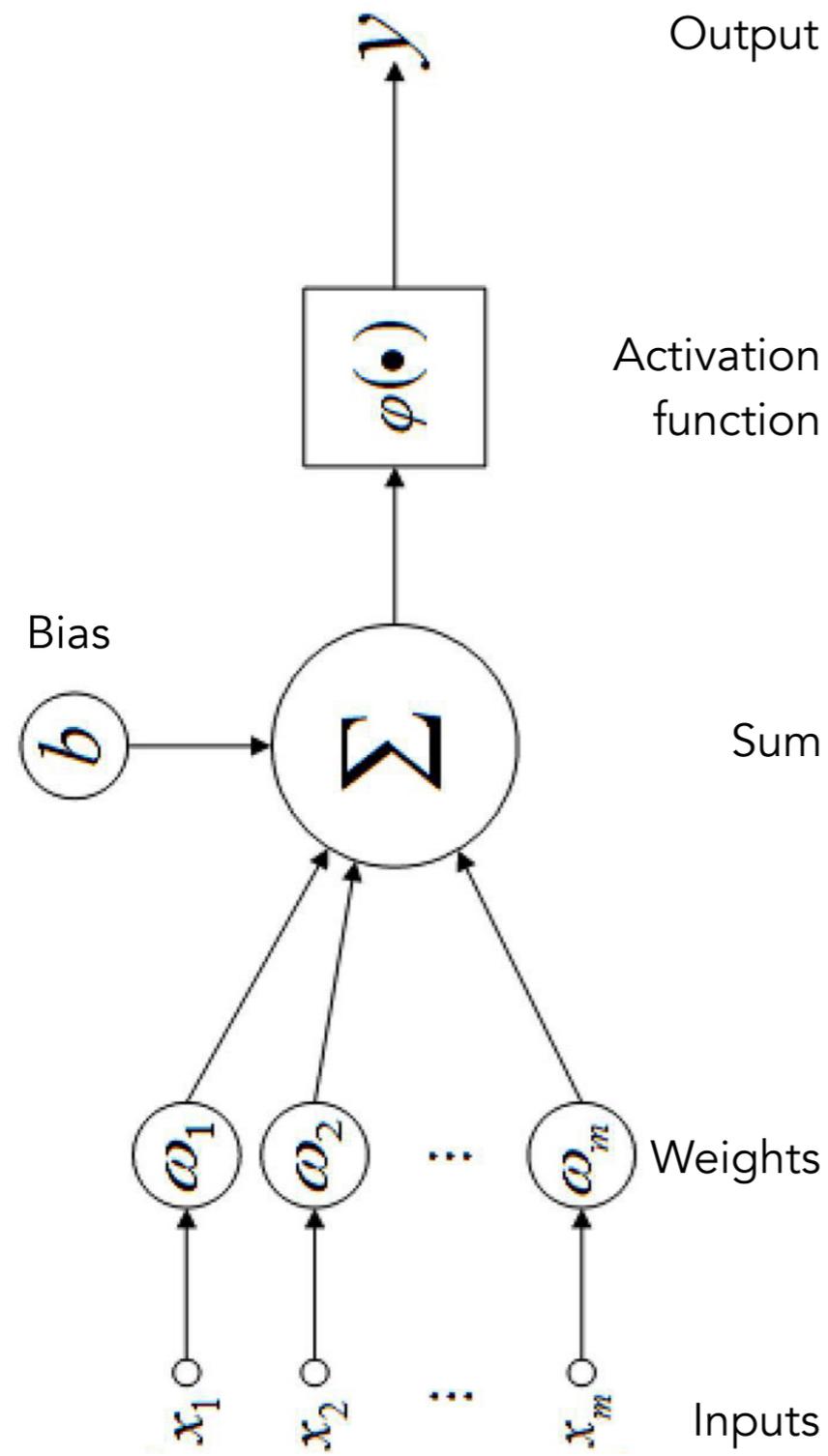


Synaptic connection

Dendrites

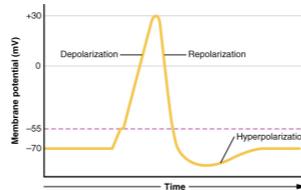
Axon terminals (from other neurons)





Polarization threshold

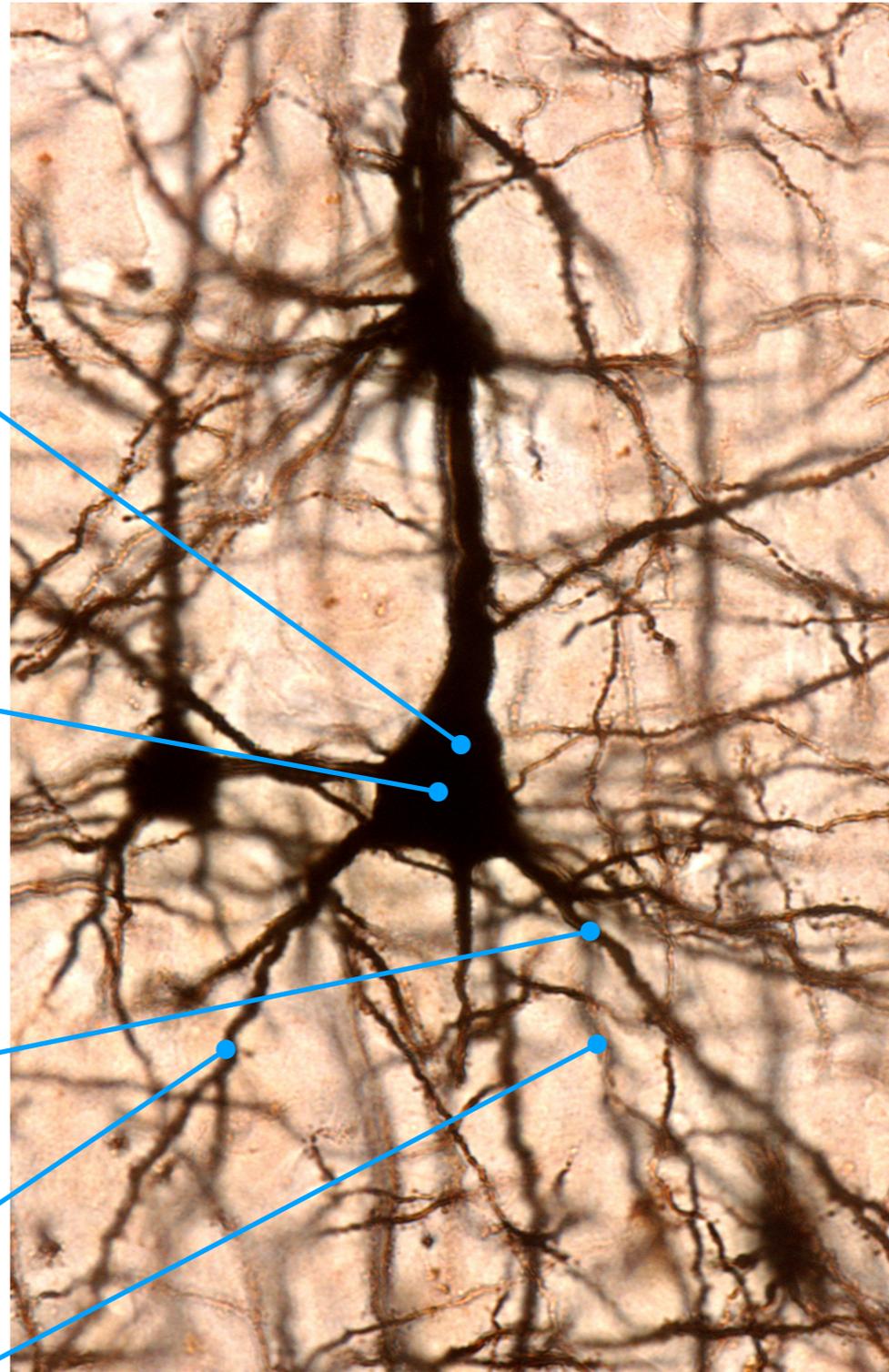
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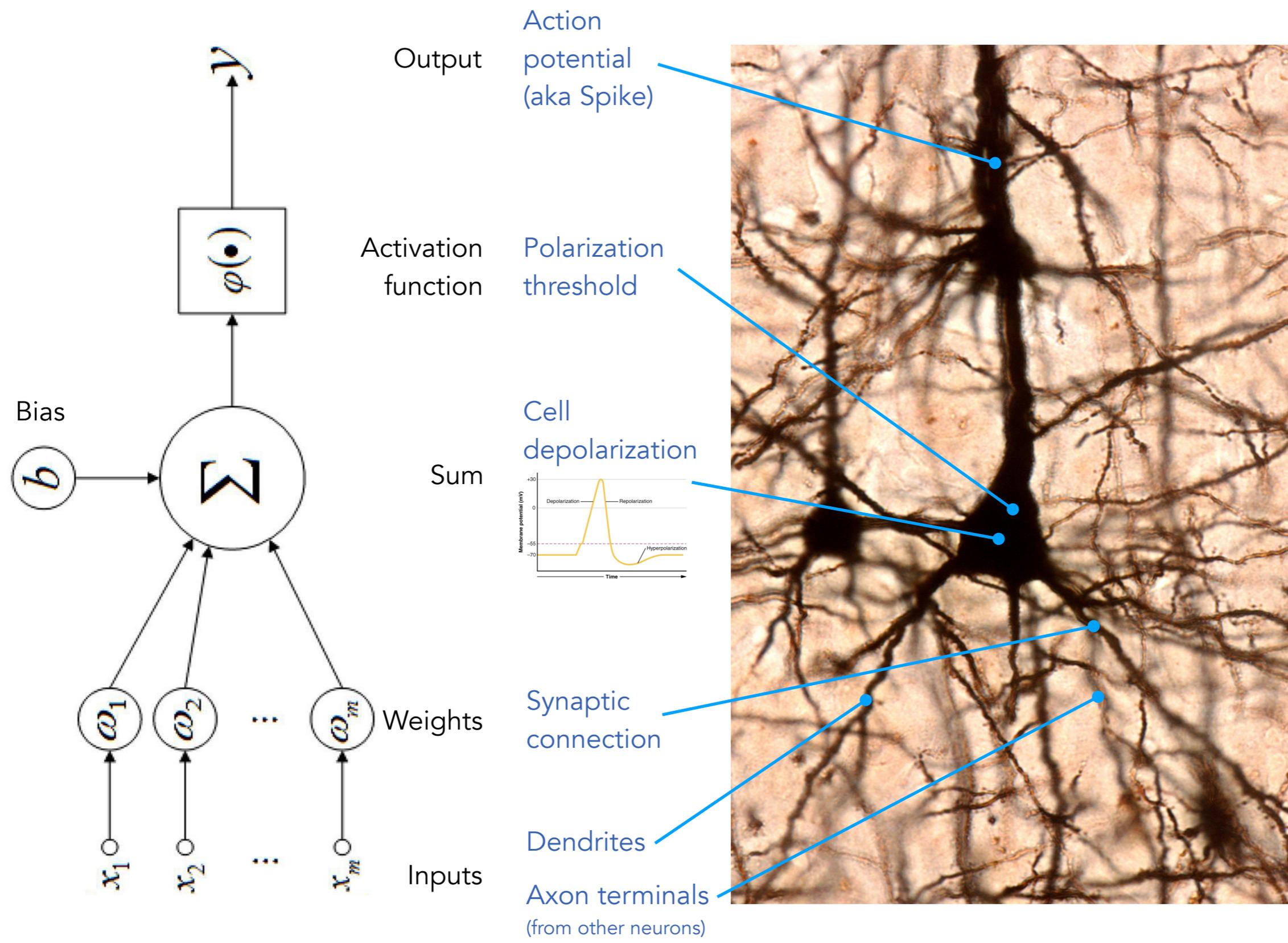


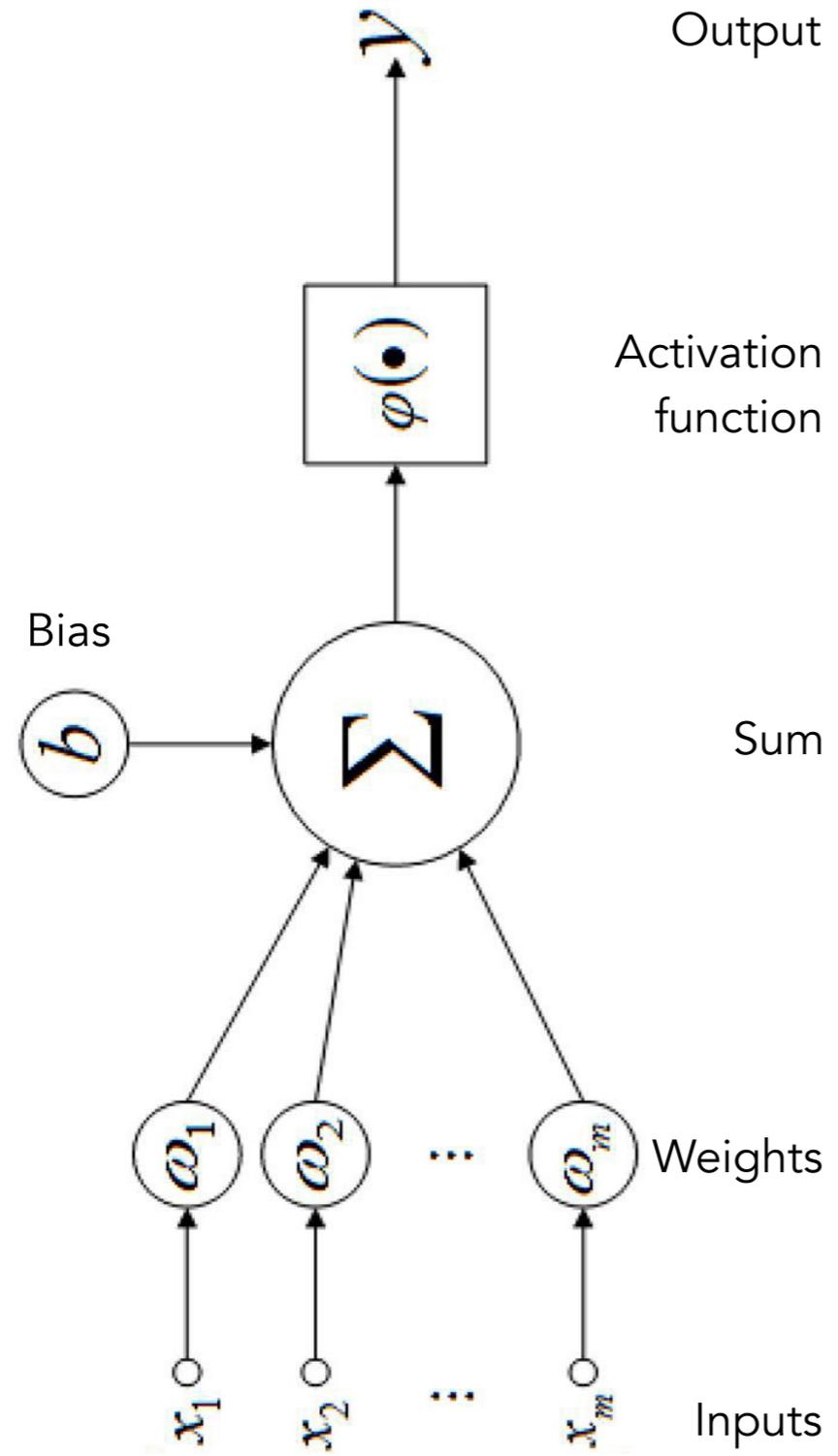
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Axon terminals
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Action potential (aka Spike)

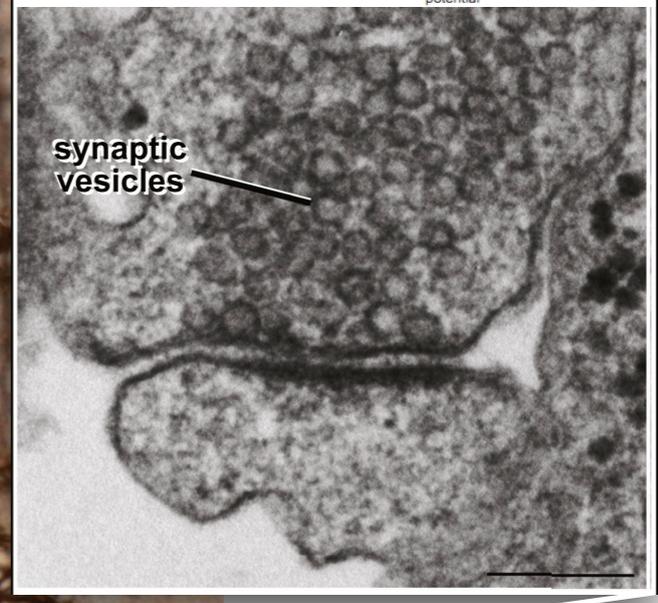
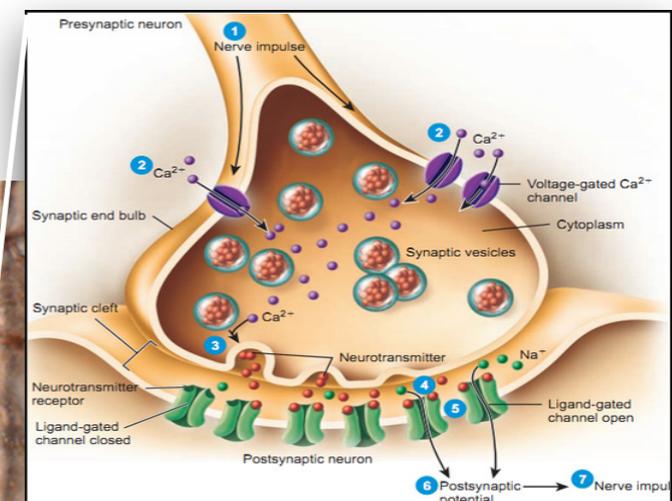
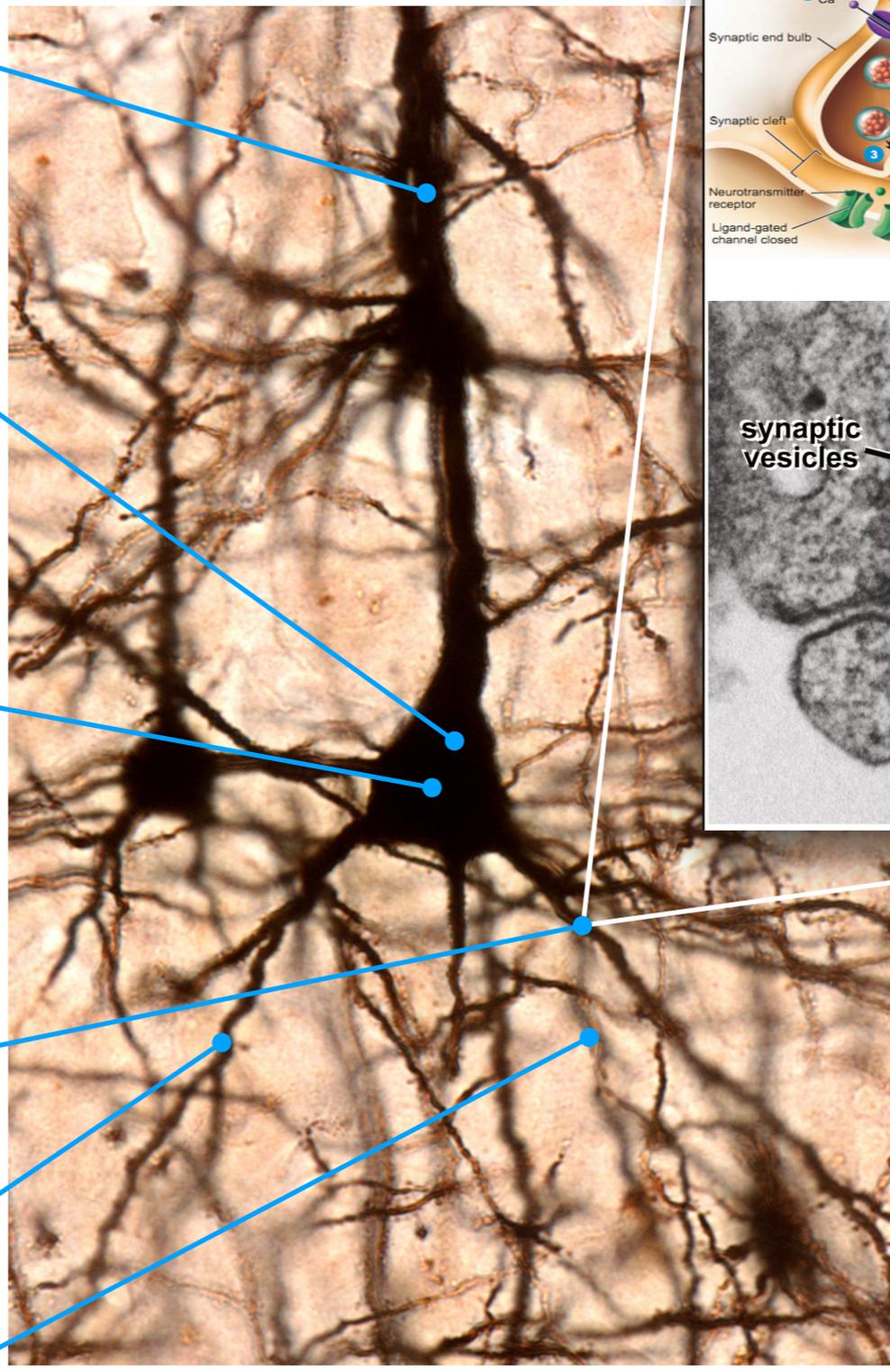
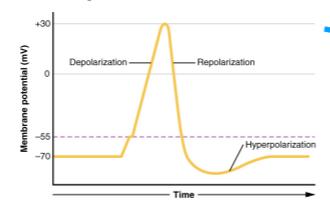
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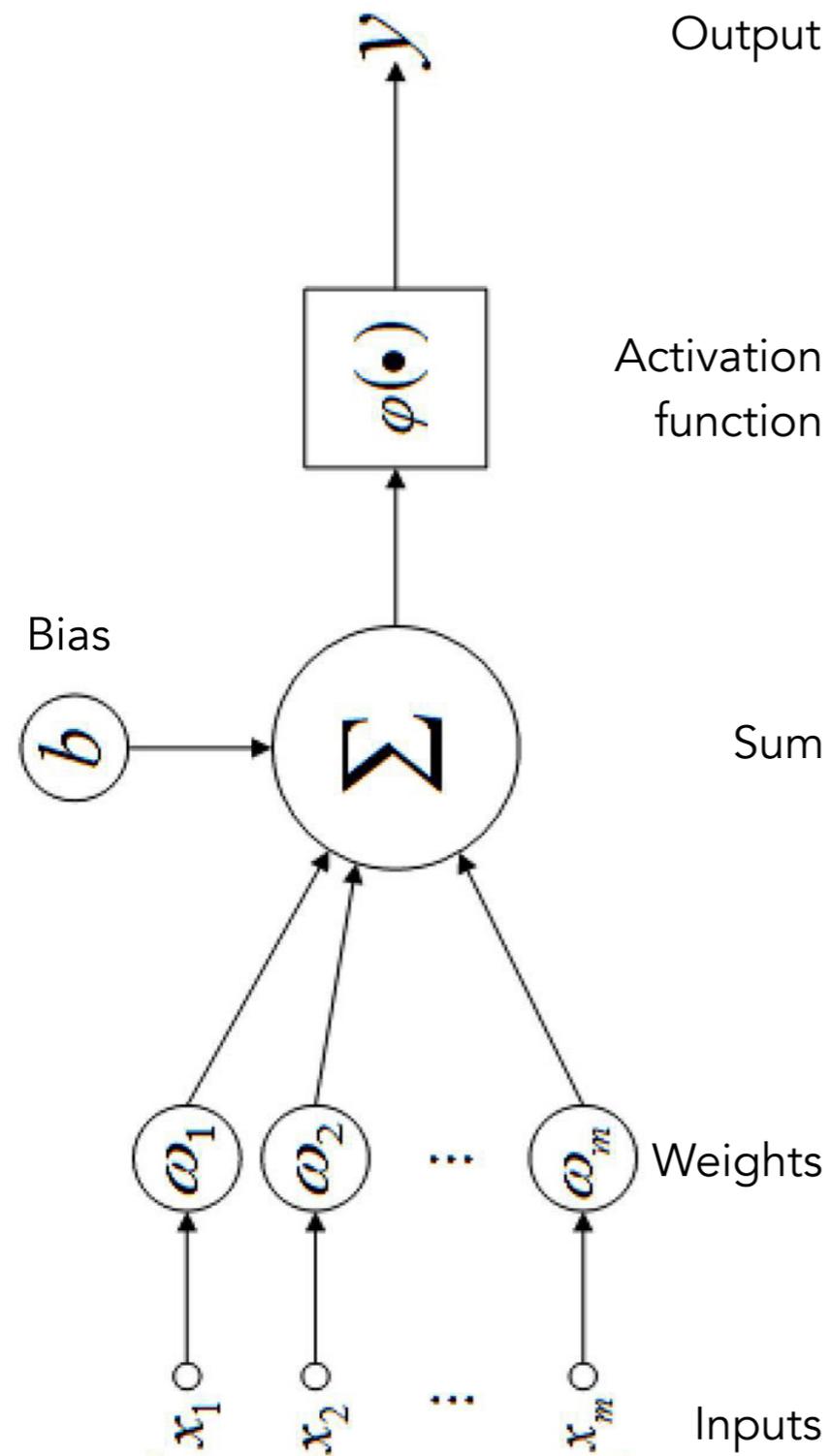
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Axon terminals (from other neurons)





Output

Activation function

Sum

Weights

Inputs

Action potential (aka Spike)

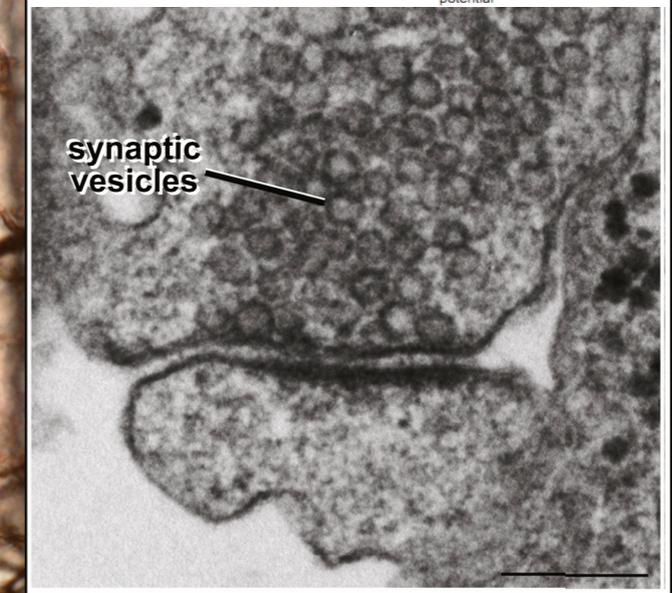
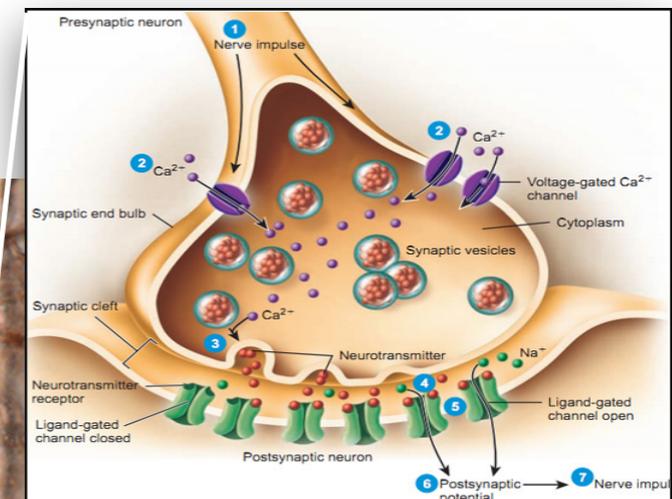
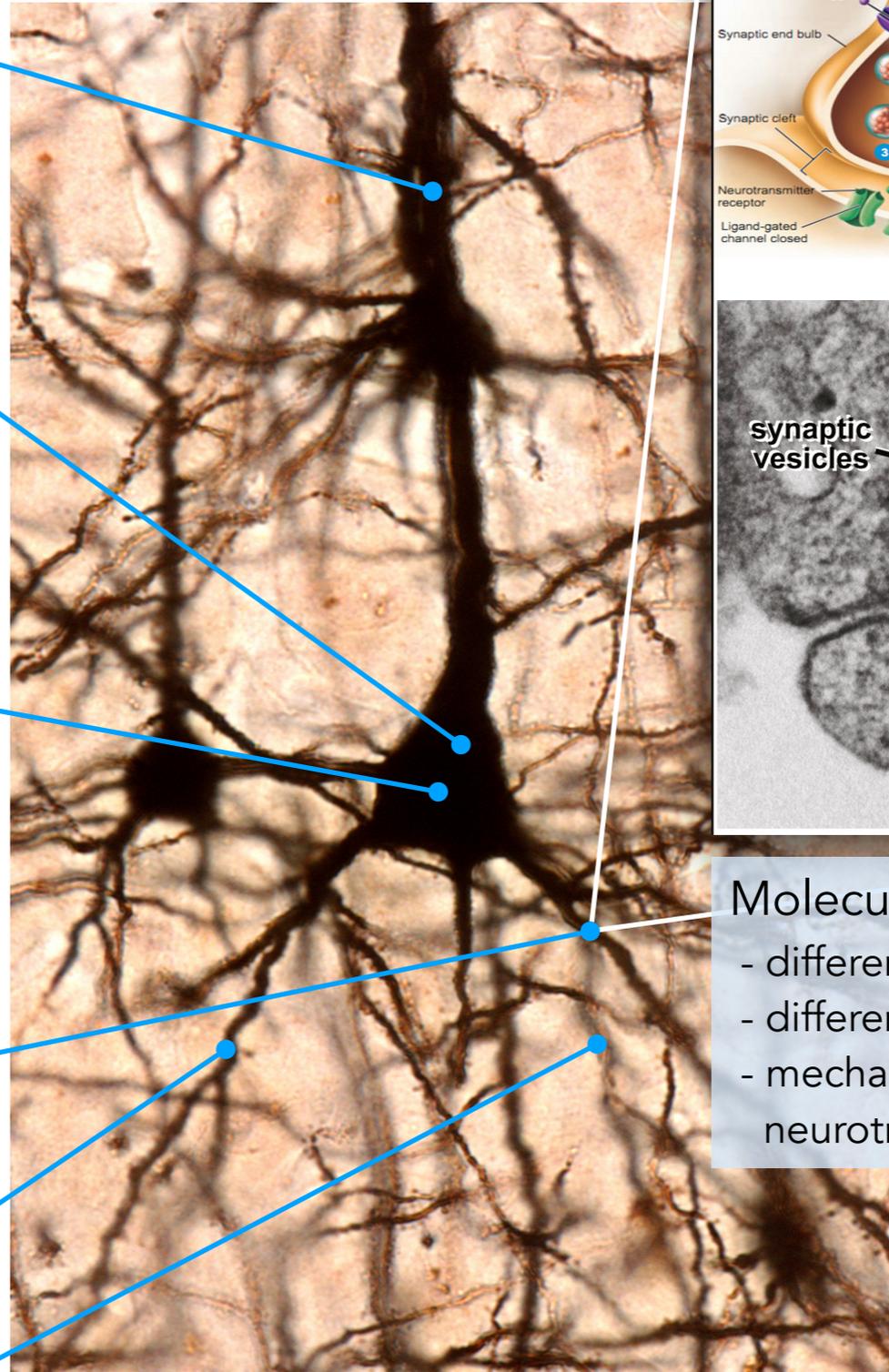
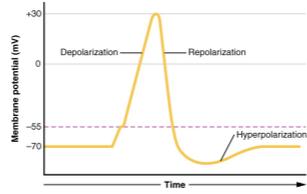
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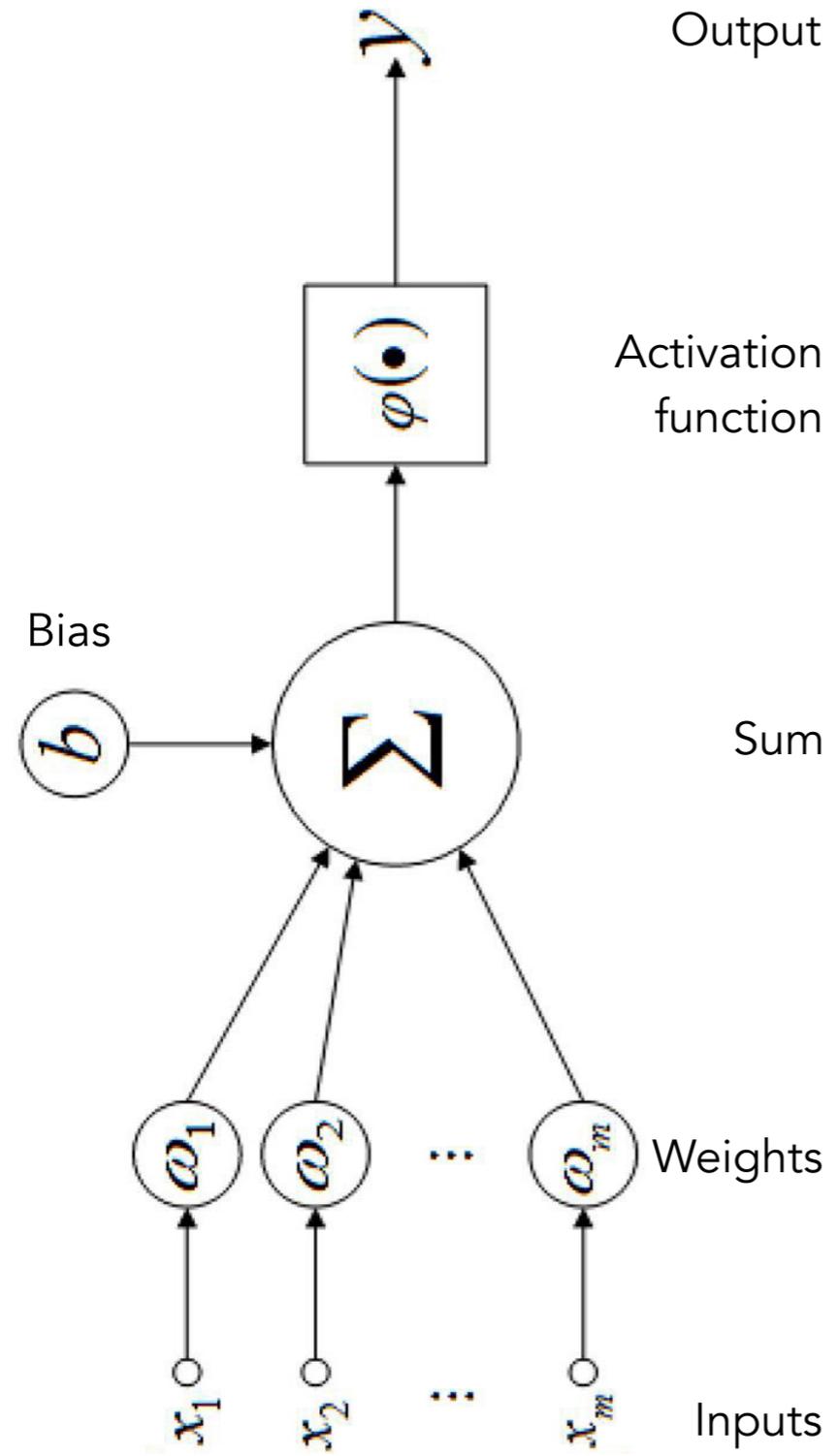
Dendrites

Axon terminals (from other neurons)



Molecular neurobiology

- different types of channels
- different receptors
- mechanism of neurotransmitter release



Action potential (aka Spike)

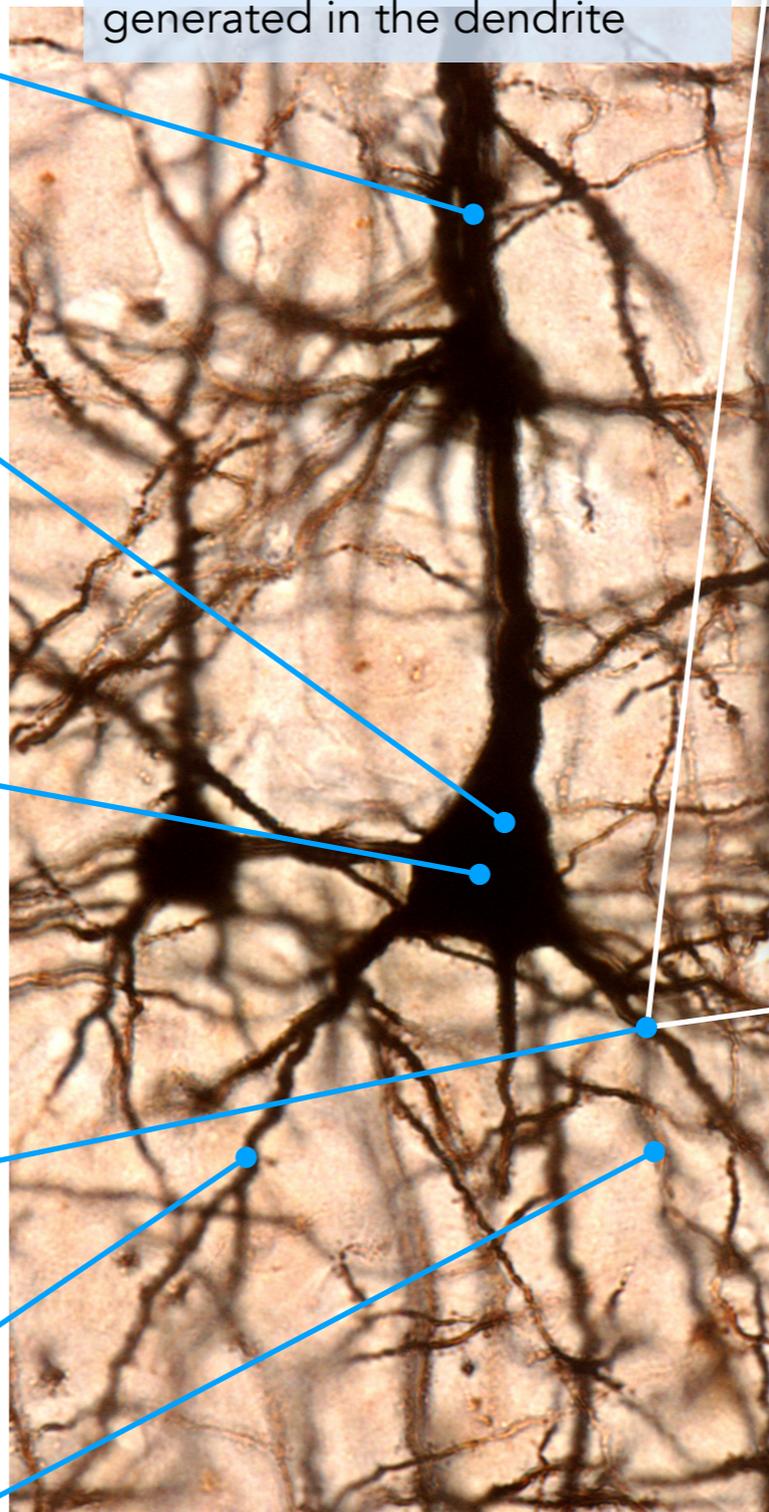
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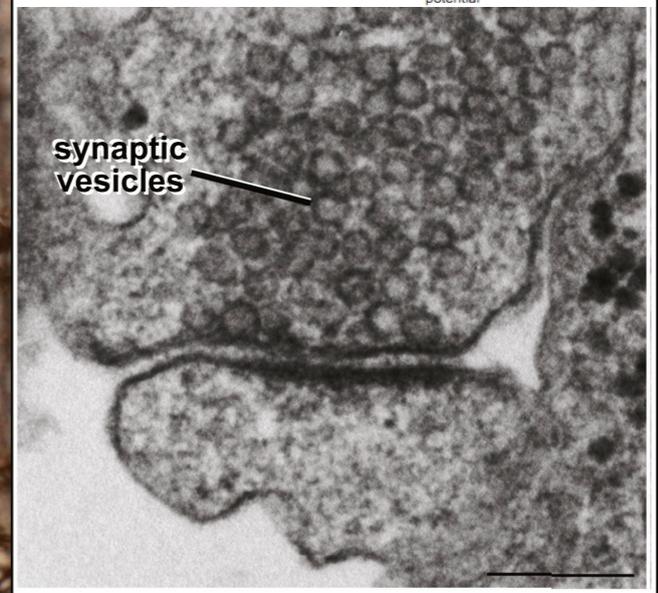
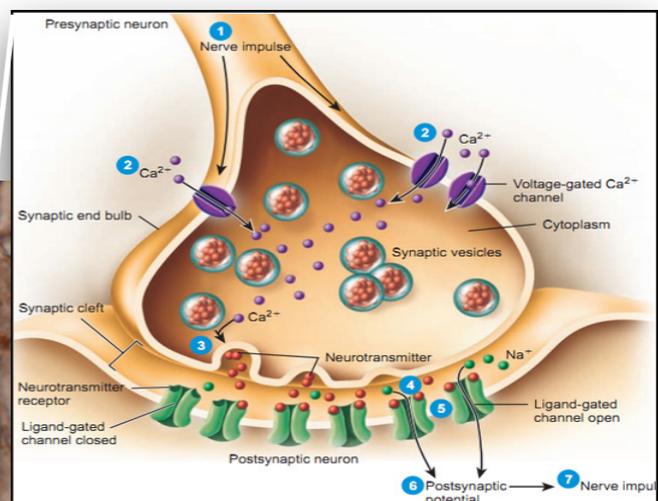
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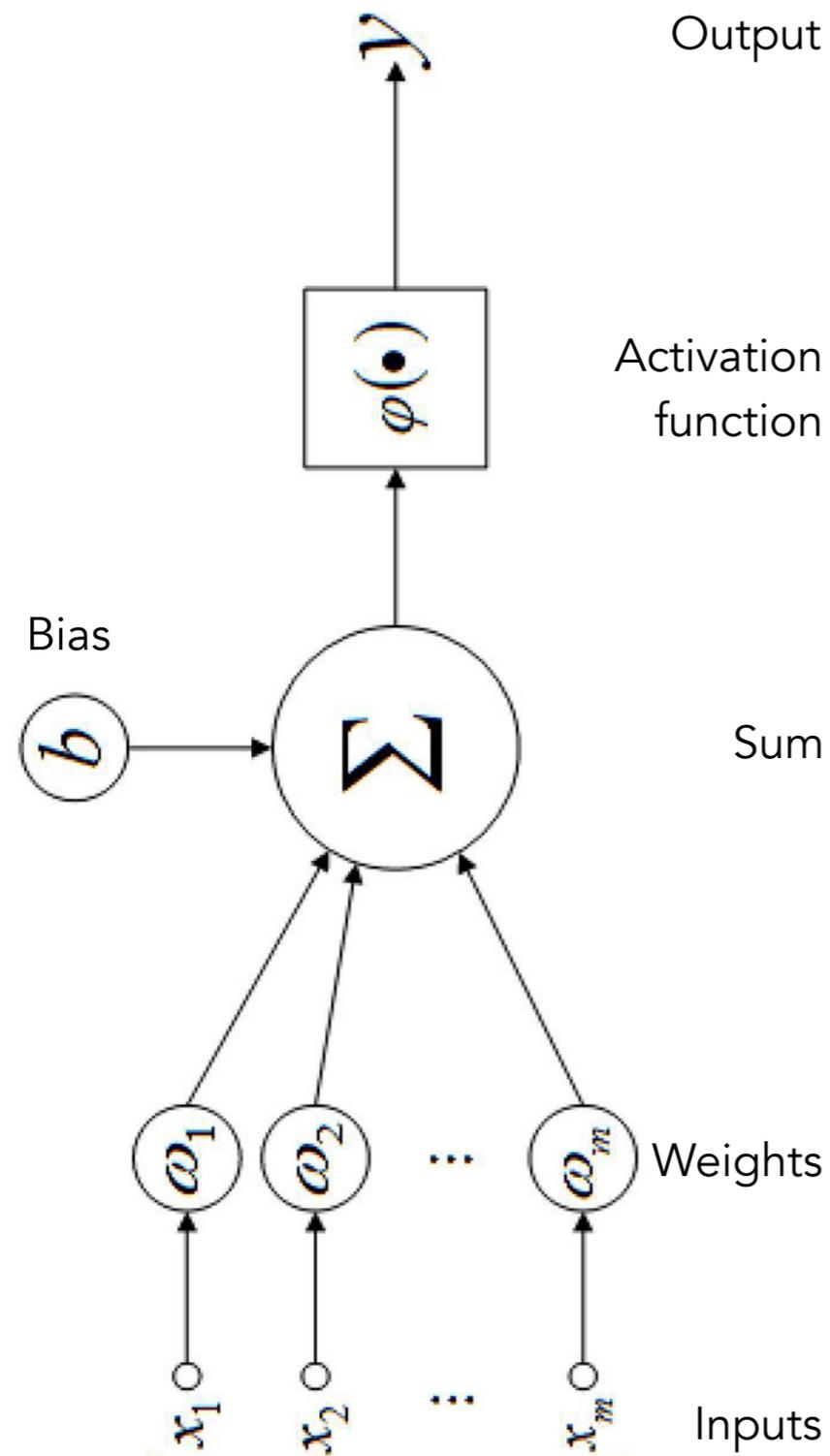


Dendritic spike action potential can be generated in the dendrite



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- different types of channels
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Output

Activation function

Sum

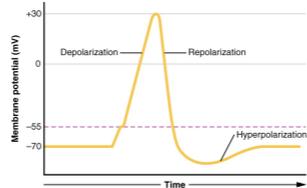
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Action potential (aka Spike)

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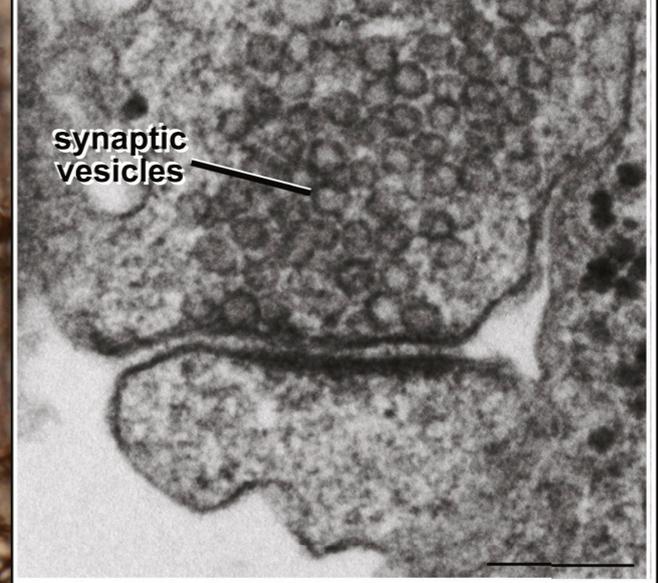
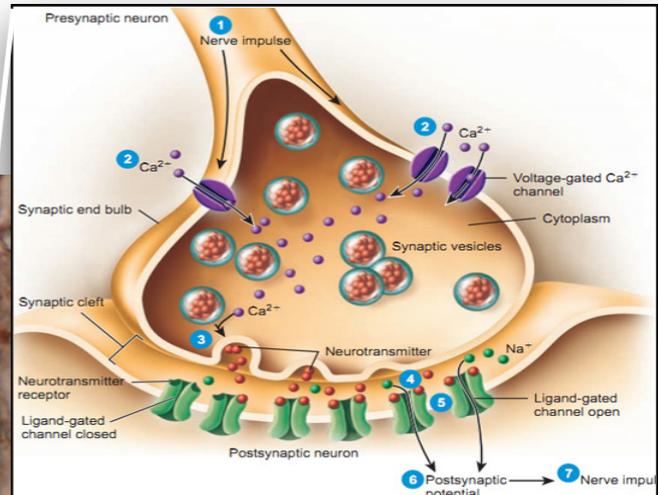
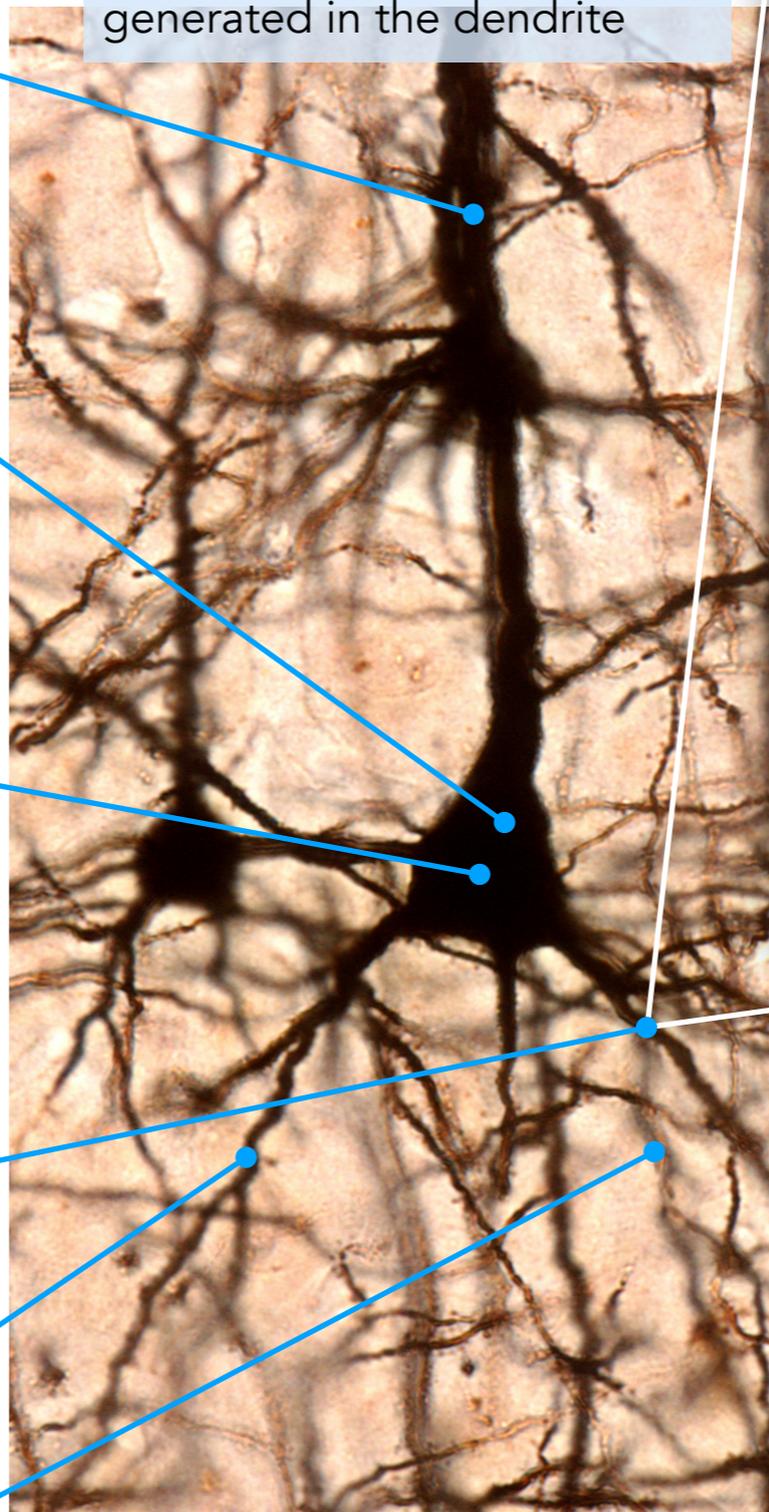


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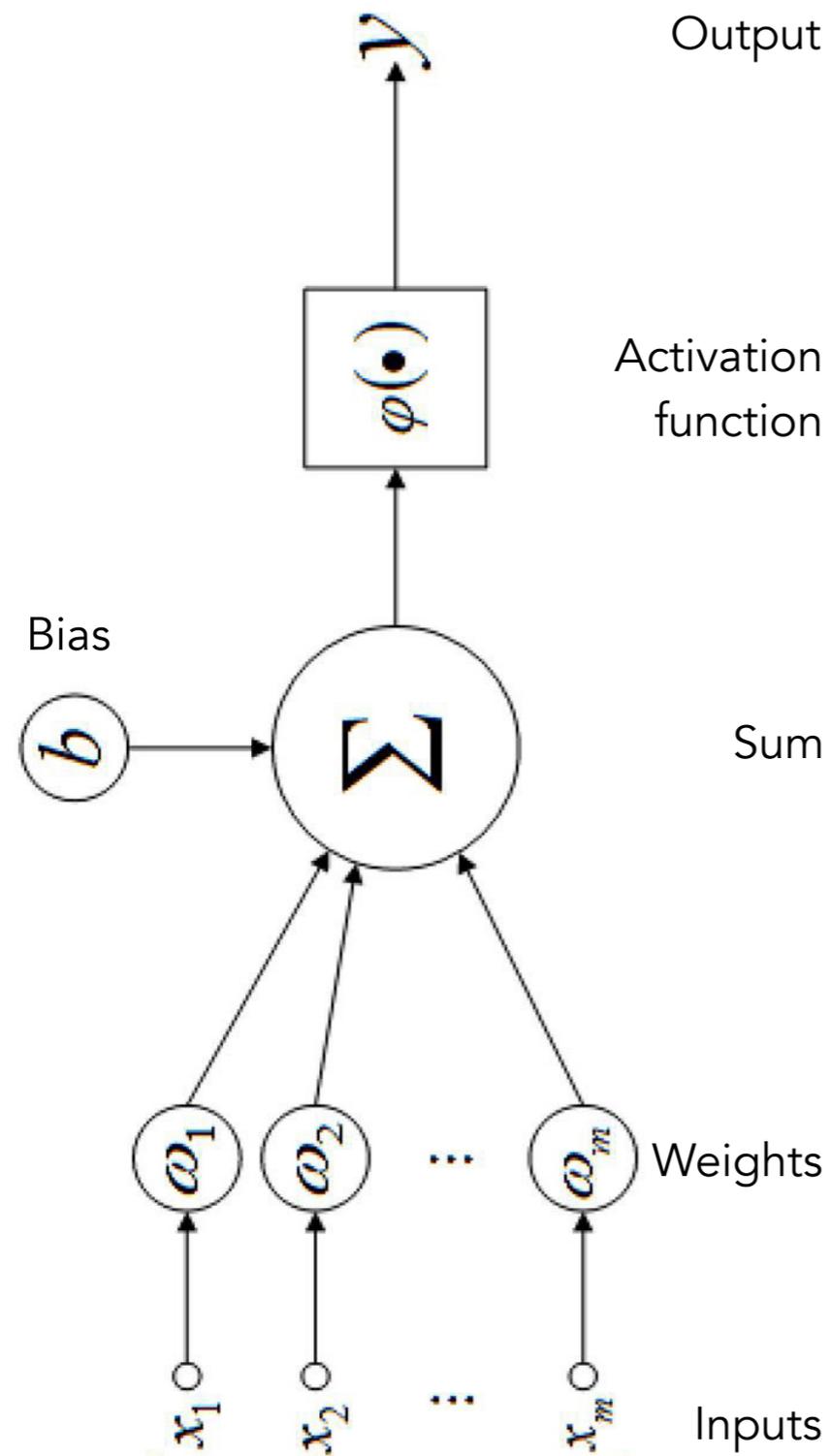


Molecular neurobiology

- different types of channels
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Timing

- no clock synchronization
- time of arrival is important



Output

Activation function

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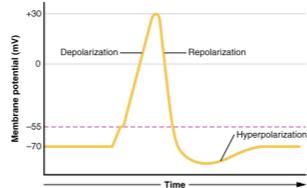
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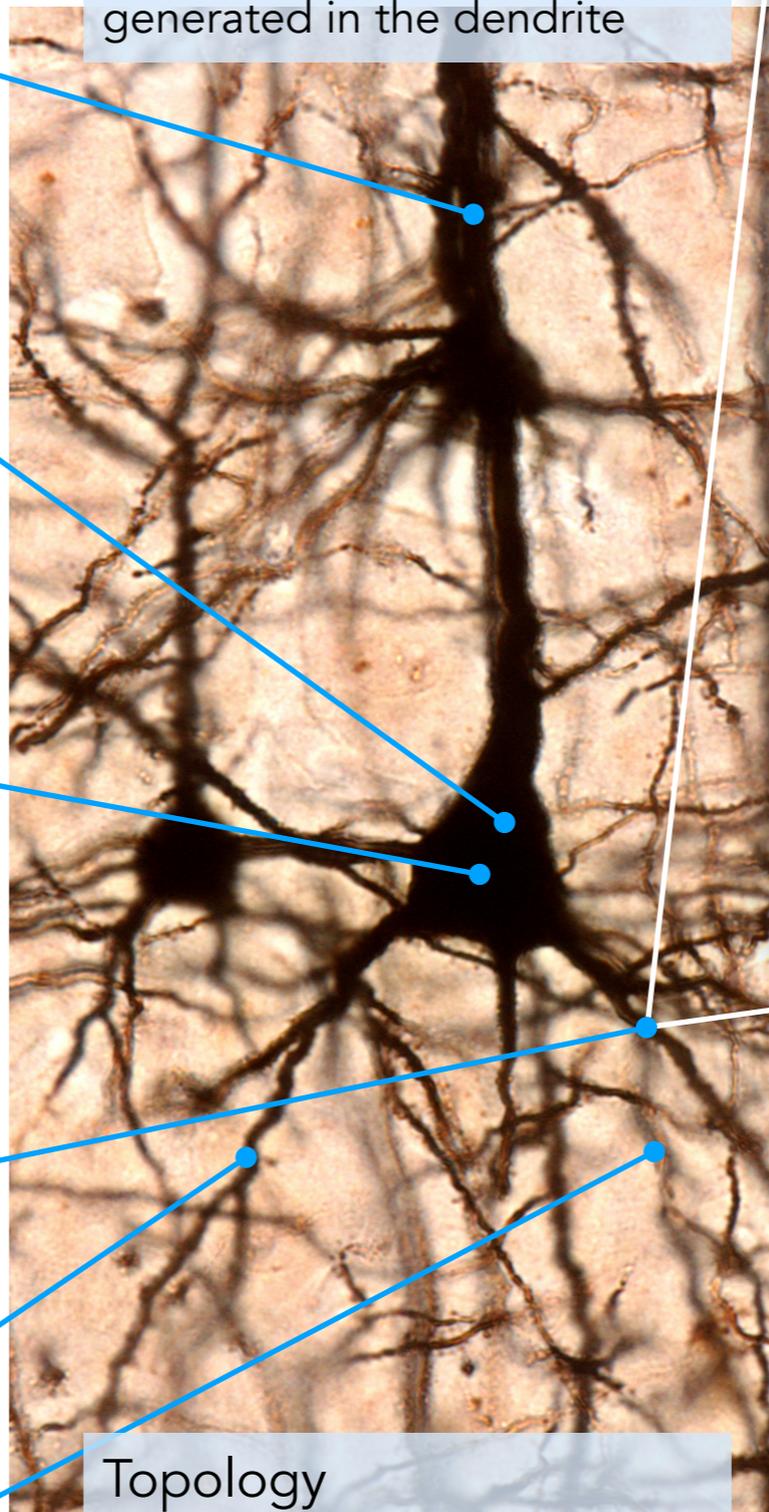


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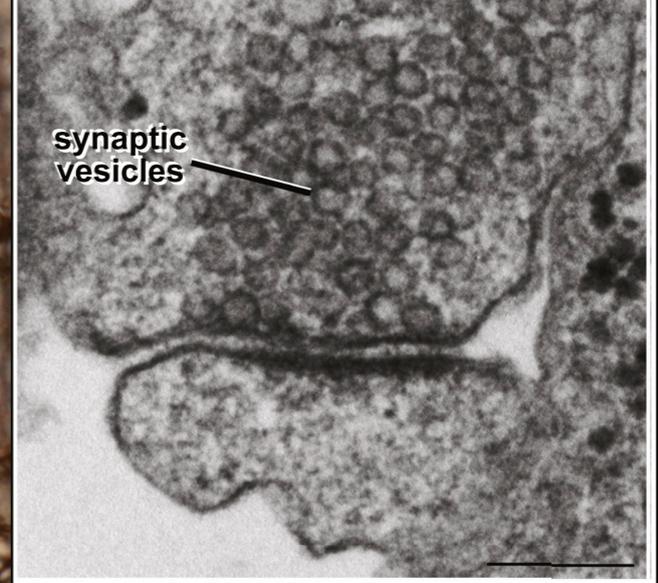
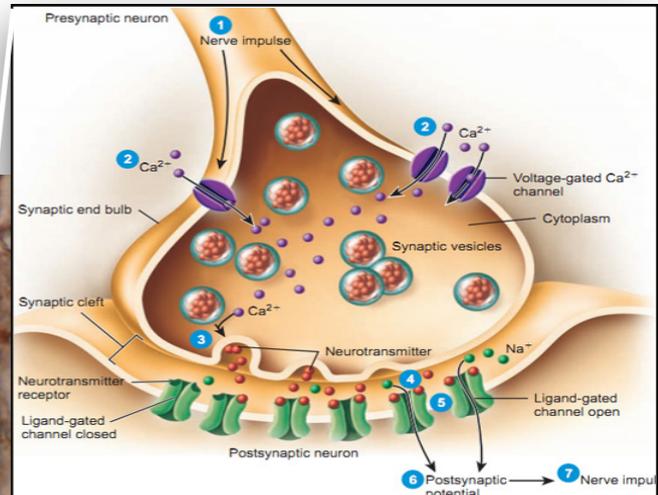
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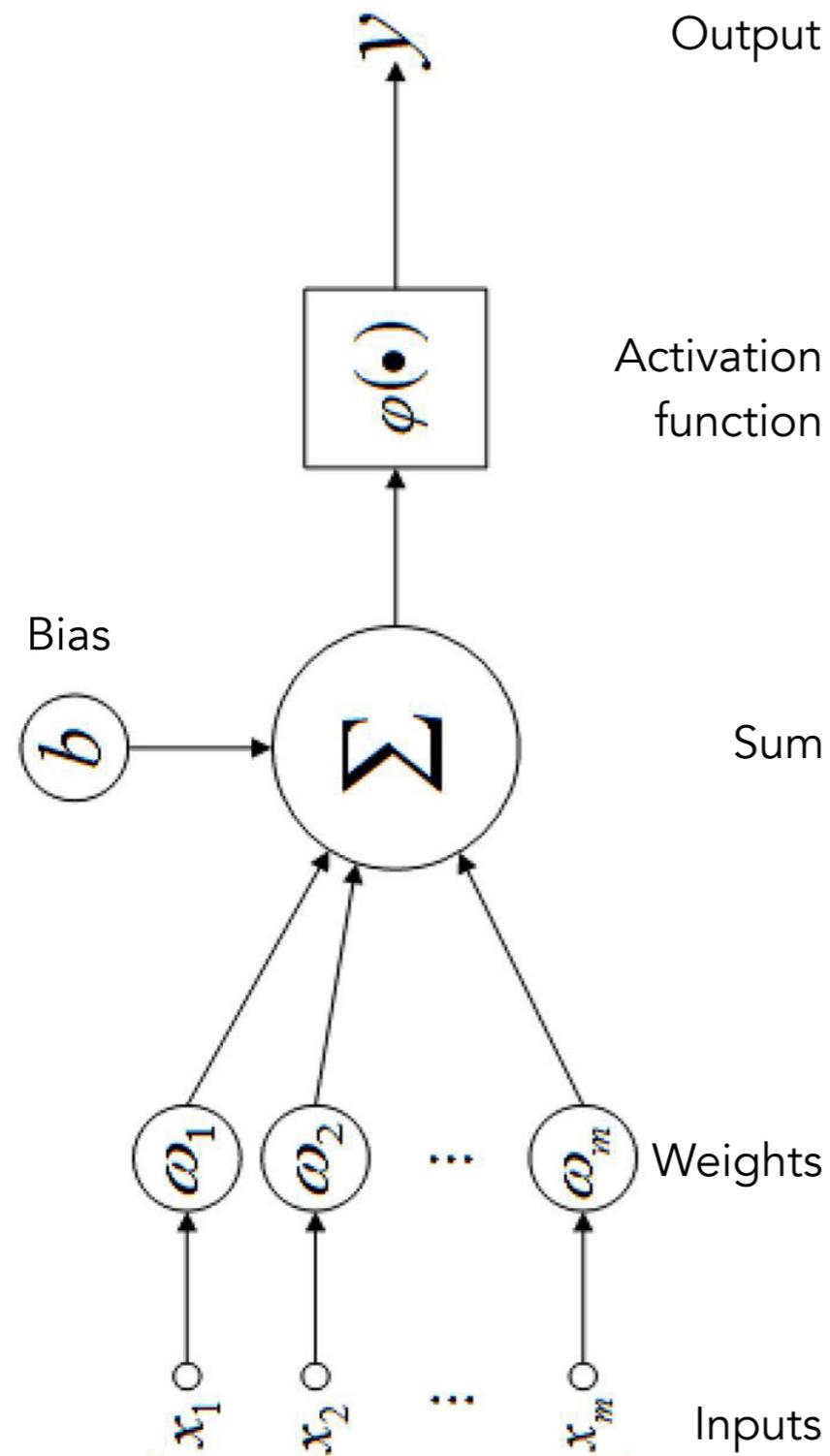


Topology
Artificial networks are neatly organized into graphs, biological network is a mess



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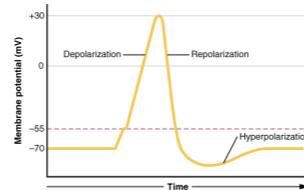
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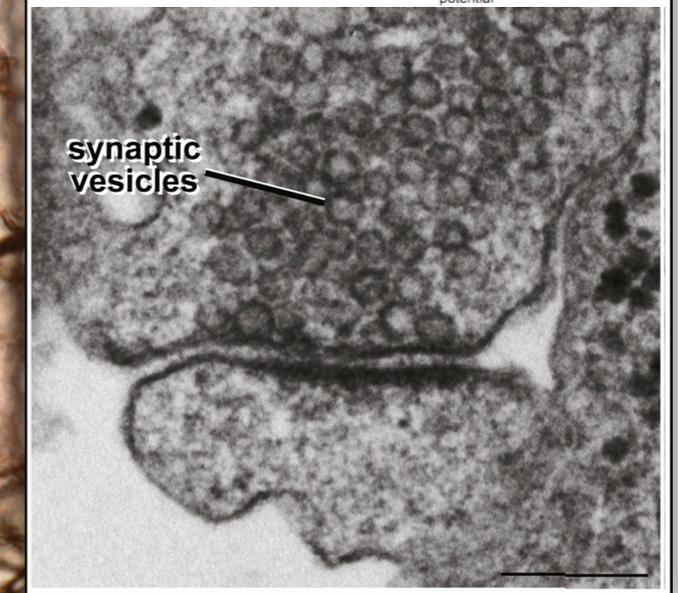
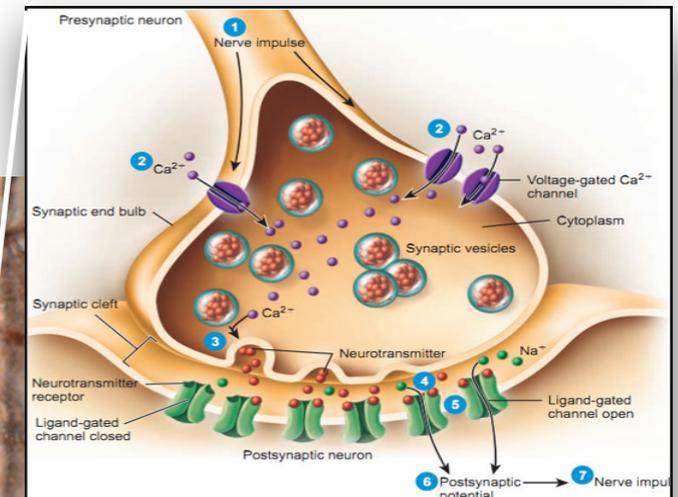
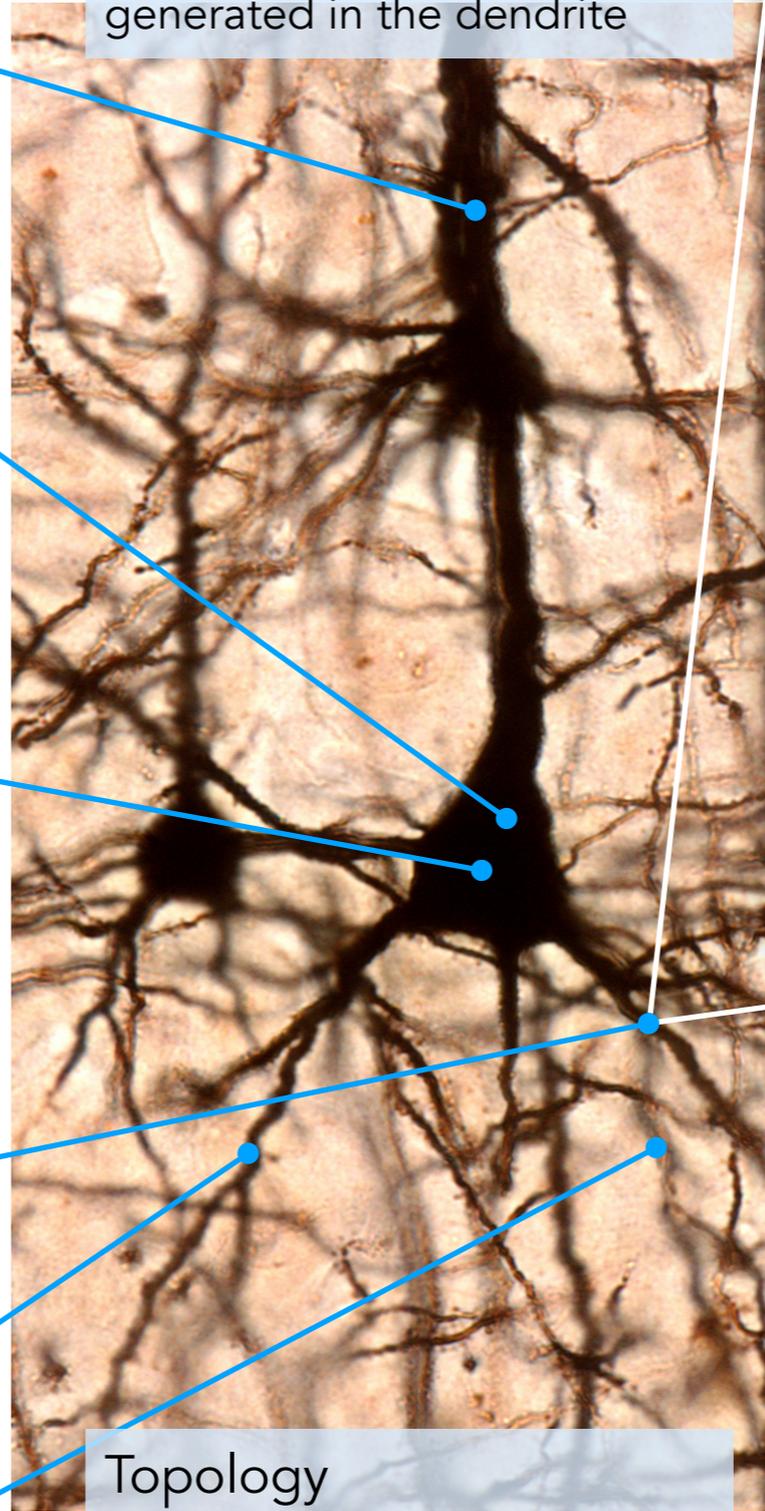
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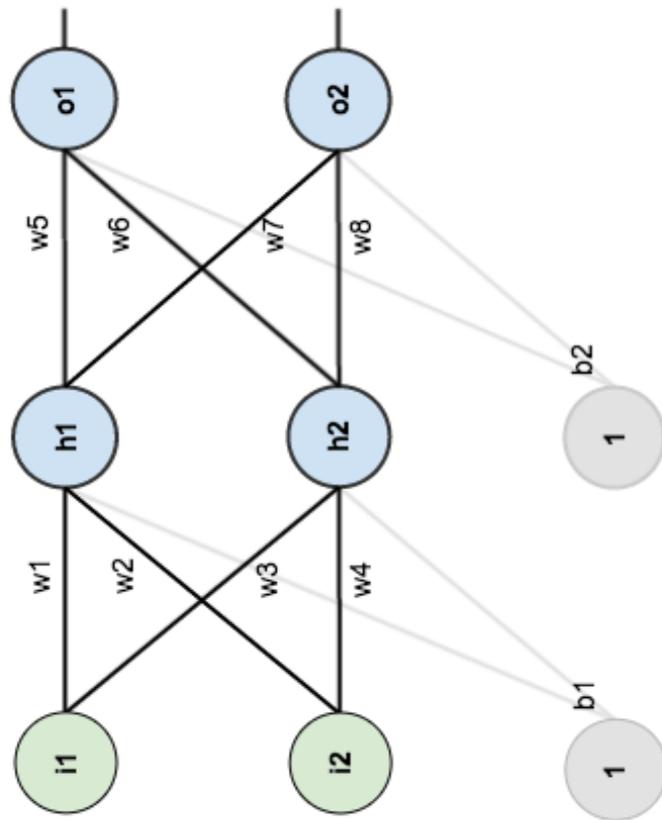
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Power consumption

Brain uses 20 watt, one Titan X — 250 watt

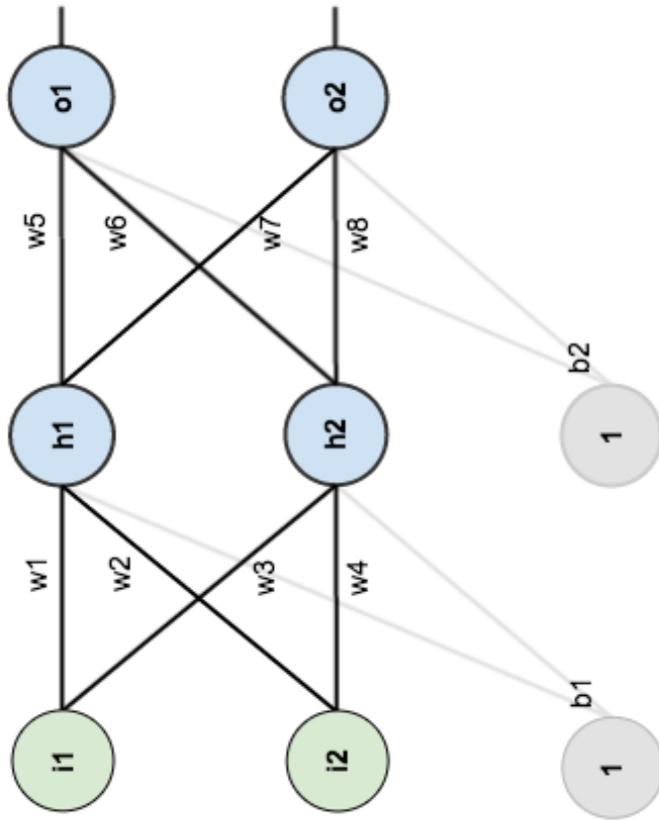
The brain cannot be doing **backpropagation**

(at least not the way we do it)



The brain cannot be doing backpropagation

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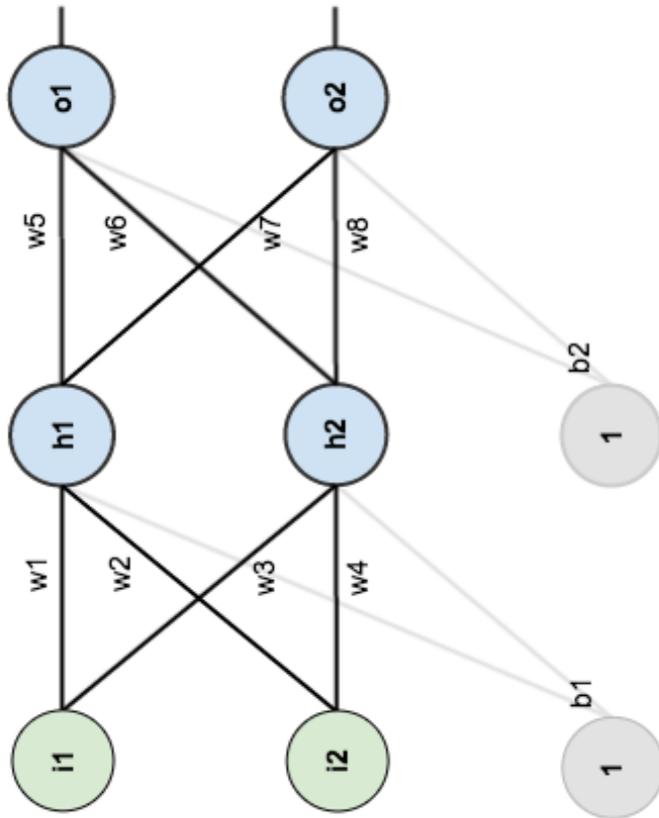
Forward pass

$$E_{o1} = \frac{1}{2}(target_{o1} - out_{o1})^2$$

$$E_{total} = E_{o1} + E_{o2}$$

The brain cannot be doing backpropagation

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Forward pass

$$E_{o1} = \frac{1}{2}(\text{target}_{o1} - \text{out}_{o1})^2$$

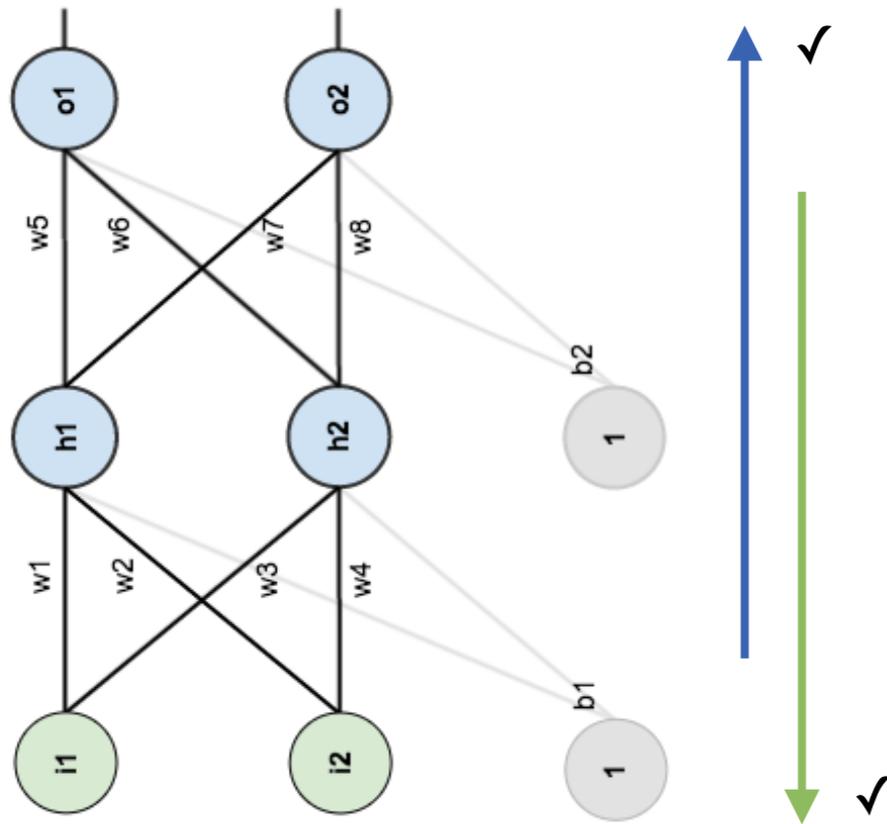
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Backwards pass

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial \text{out}_{o1}} * \frac{\partial \text{out}_{o1}}{\partial \text{net}_{o1}} * \frac{\partial \text{net}_{o1}}{\partial w_5}$$

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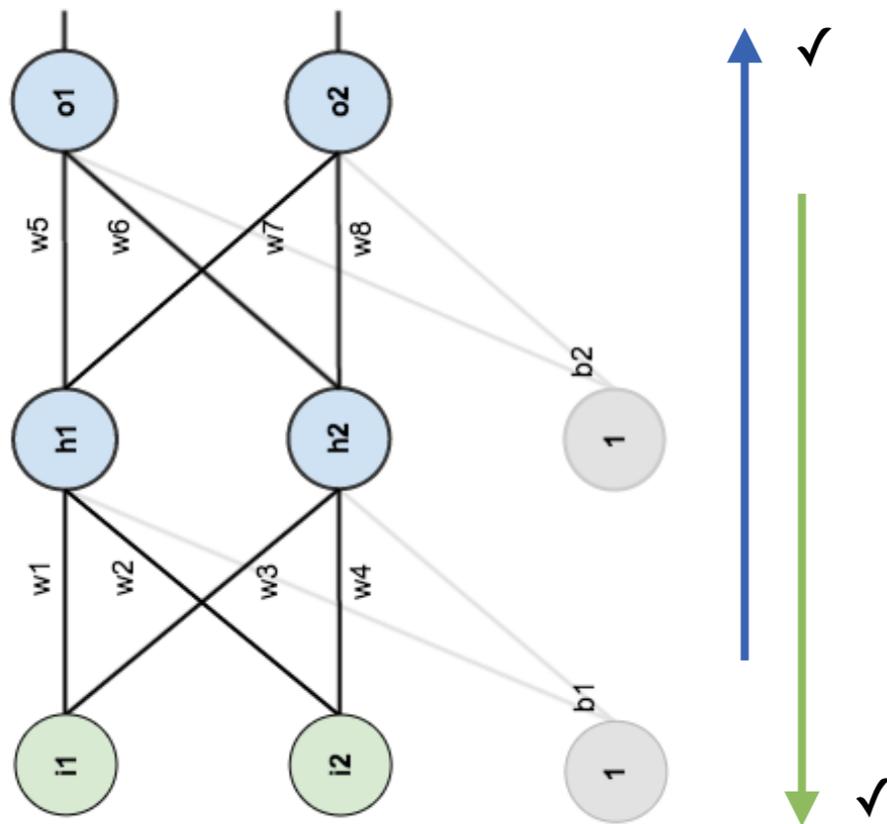
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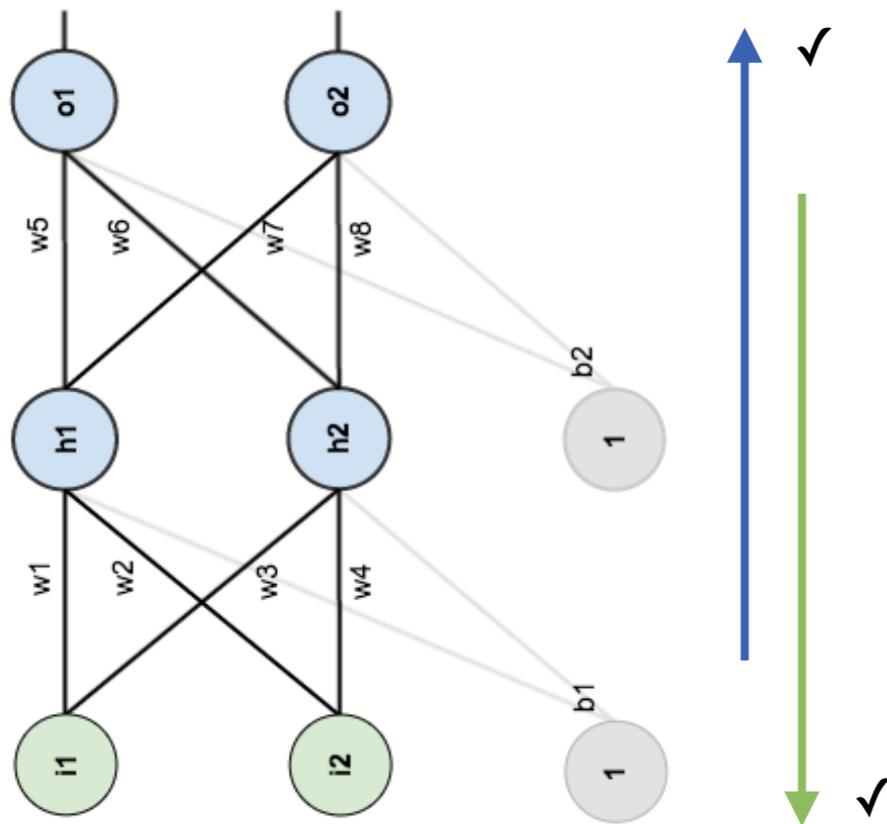
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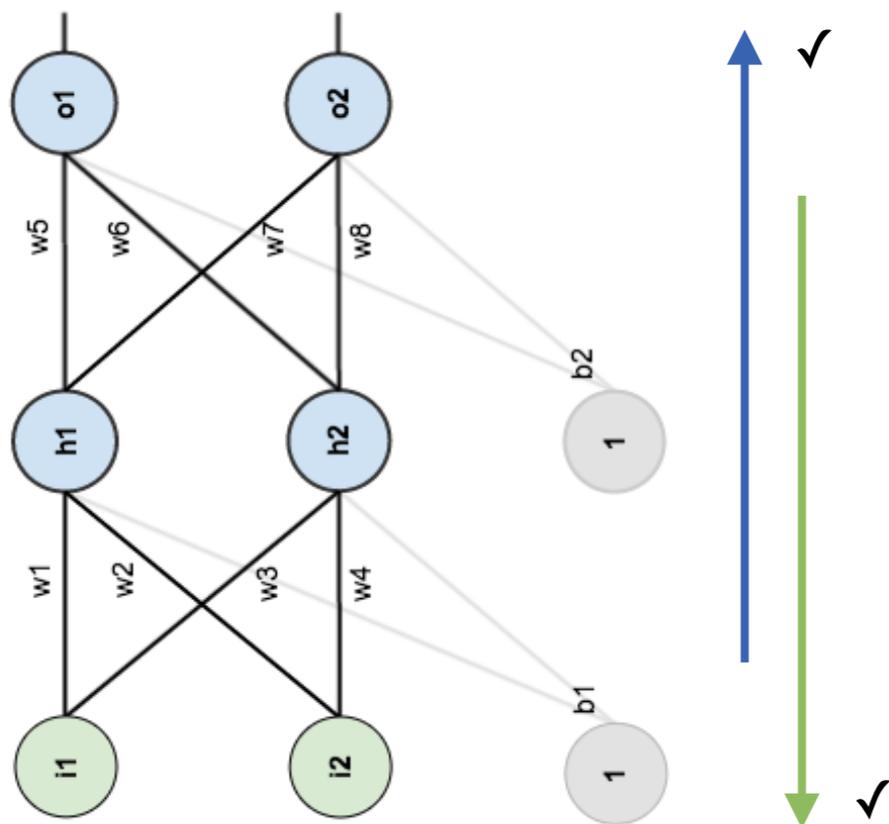


Neurons send spikes,
not real-valued outputs



The brain cannot be doing **backpropagation**

(at least not the way we do it)



Forward pass

$$E_{o1} = \frac{1}{2}(target_{o1} - out_{o1})^2$$

$$E_{total} = E_{o1} + E_{o2}$$

Backwards pass

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial w_5}$$

Forward pass



Neurons send spikes,
not real-valued outputs

Backwards pass

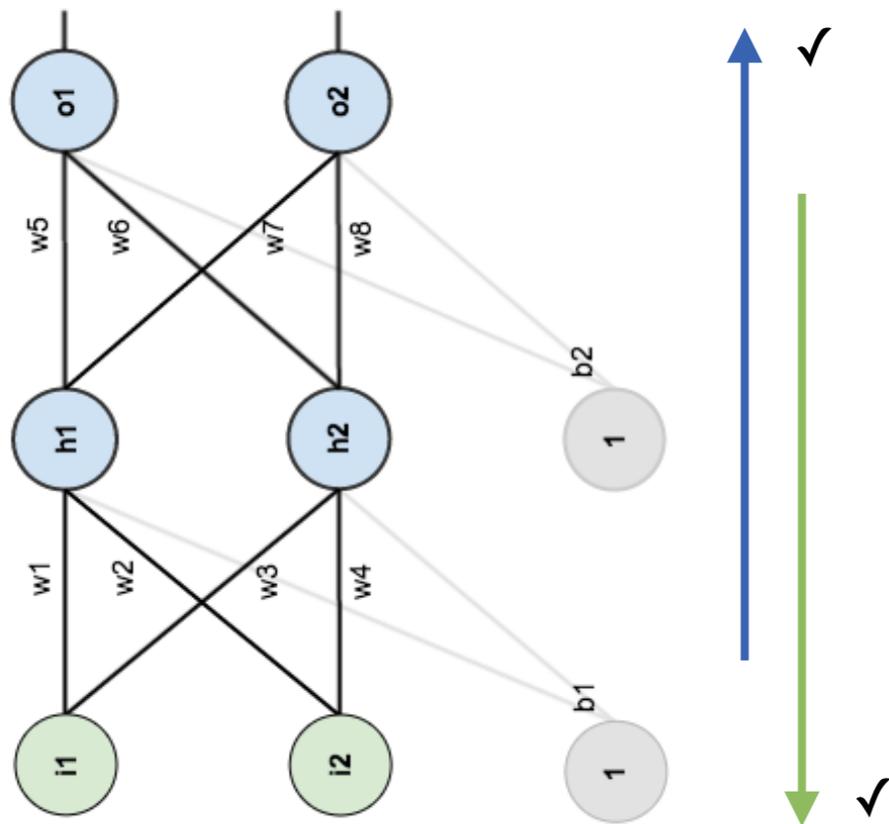
Neurons would need
bidirectional connections
with the same weight

Neurons would need to
send two types of signal
and estimate derivative



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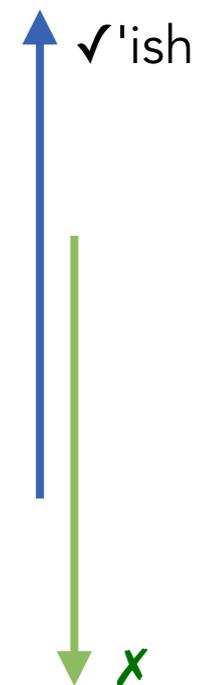
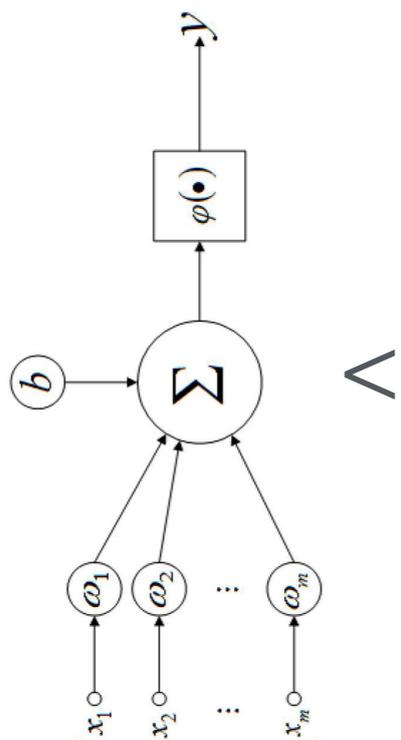
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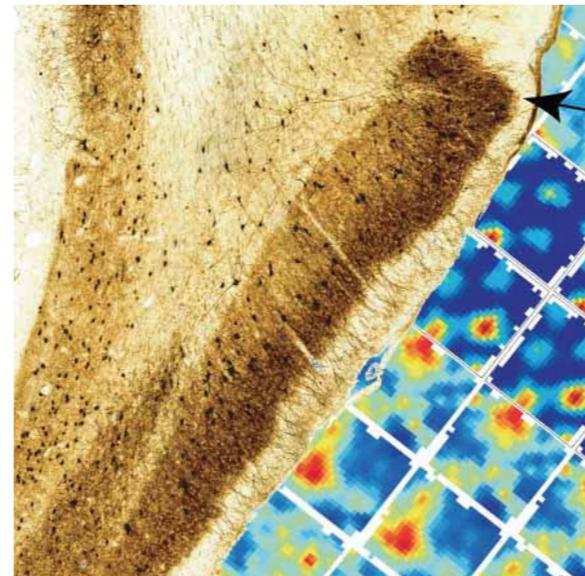
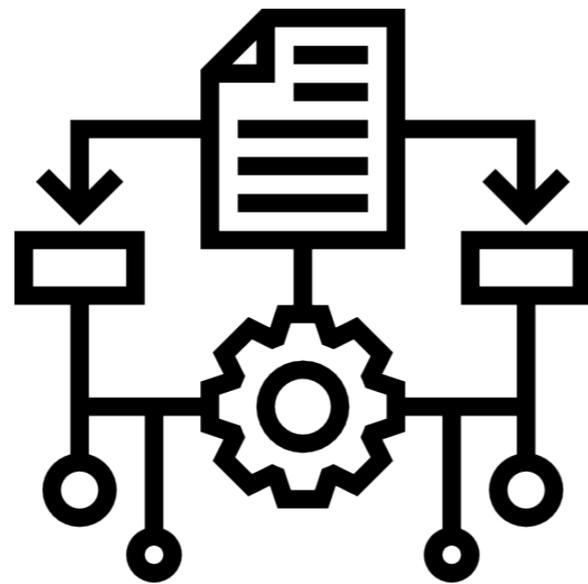
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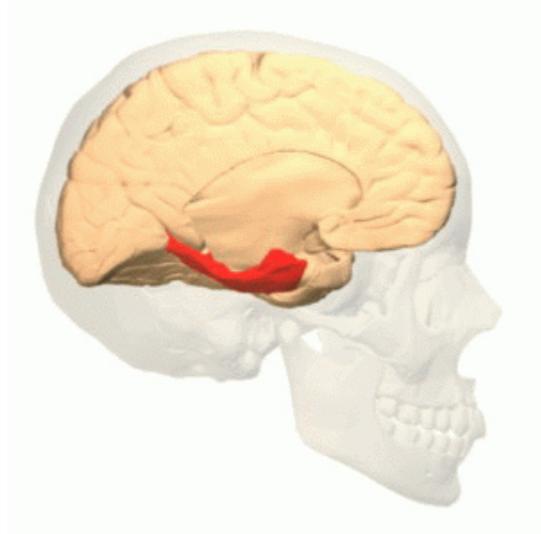


Quite different on the level of **implementation**



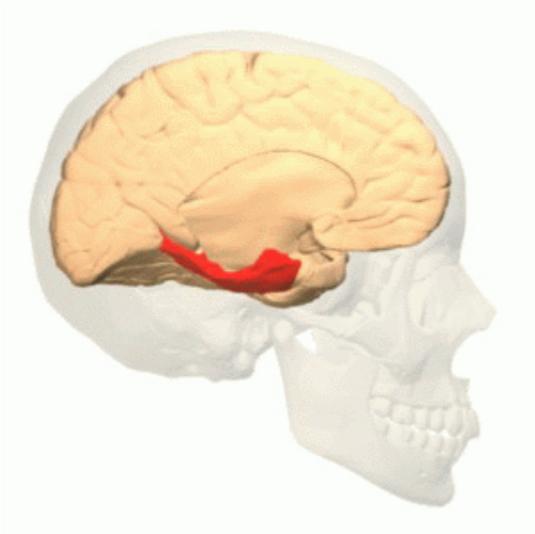
Algorithm and representation

Hippocampus and experience **replay**



Hippocampus

Hippocampus and experience **replay**



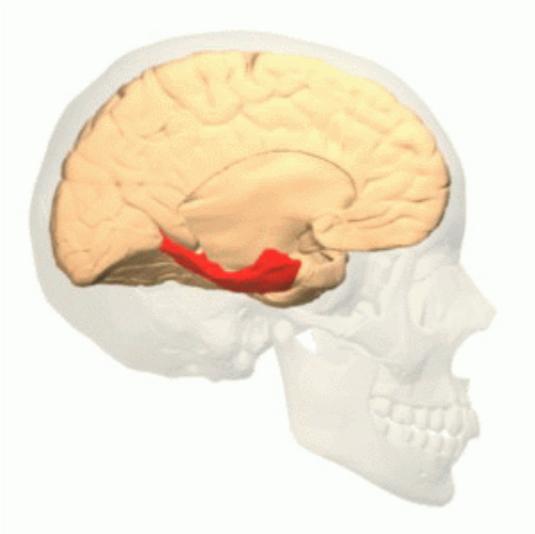
Hippocampus



Memory consolidation

From Wikipedia, the free encyclopedia

Hippocampus and experience **replay**



Hippocampus



Memory consolidation

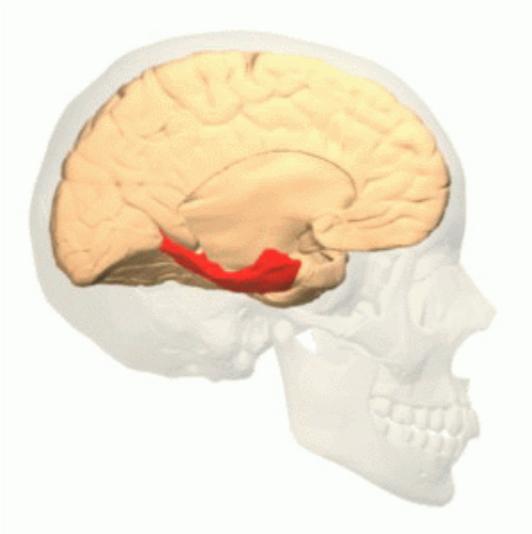
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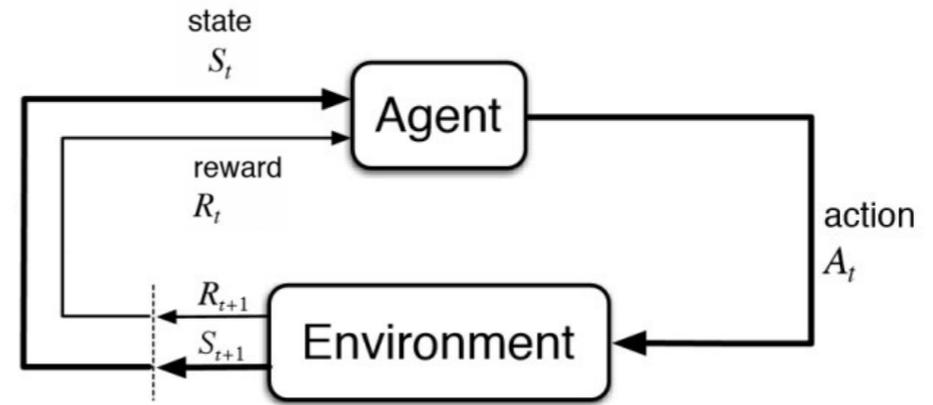
Hippocampal replay

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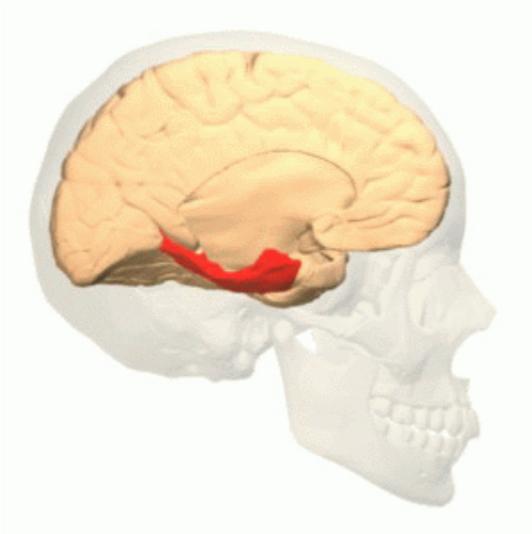
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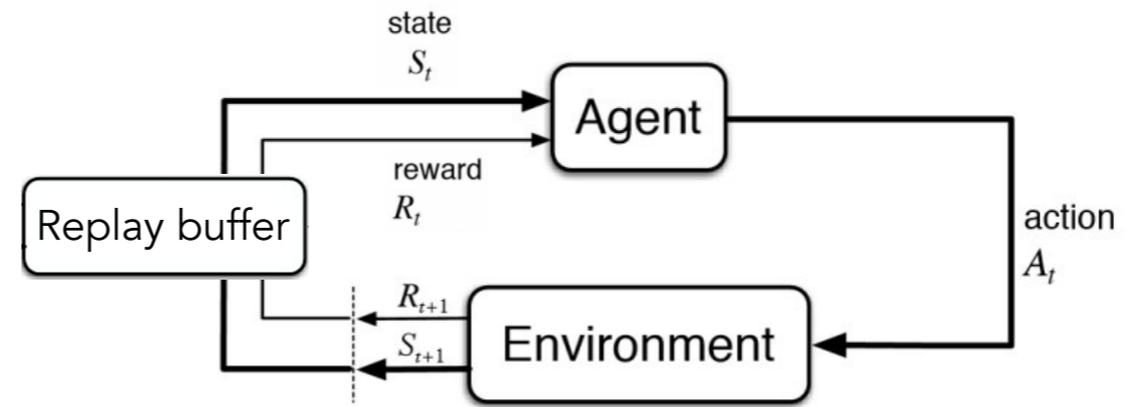
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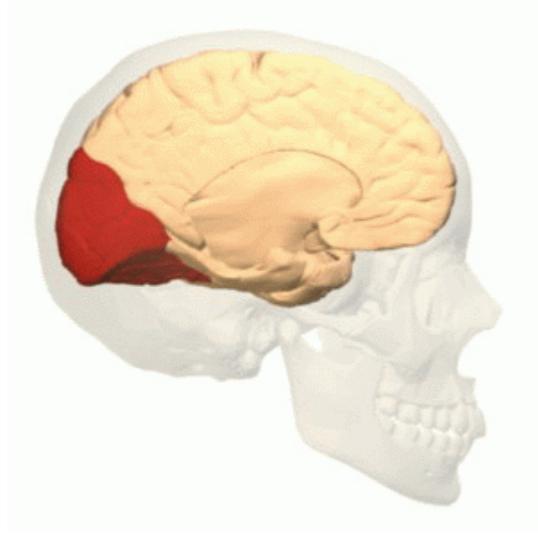
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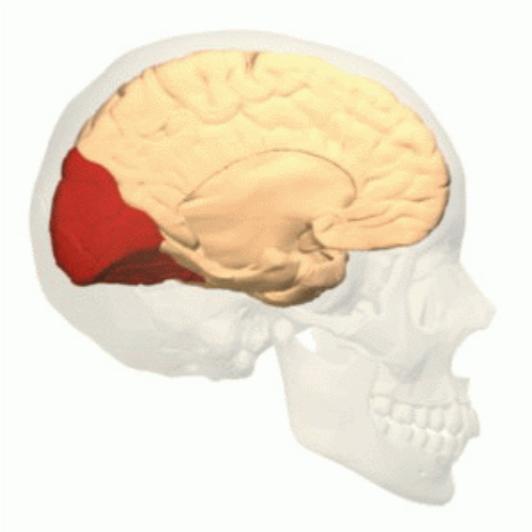
DQN algorithm has state memory buffer and **experience replay** mechanism:

- store experiences while interacting with the environment
- randomly sample and replay experiences from memory while learning

Vision: **hierarchy** of layers



Vision: **hierarchy** of layers



J. Physiol. (1959) 148, 574-591

RECEPTIVE FIELDS OF SINGLE NEURONES IN THE CAT'S STRIATE CORTEX

BY D. H. HUBEL* AND T. N. WIESEL*



106

J. Physiol. (1962), 160, pp. 106-154
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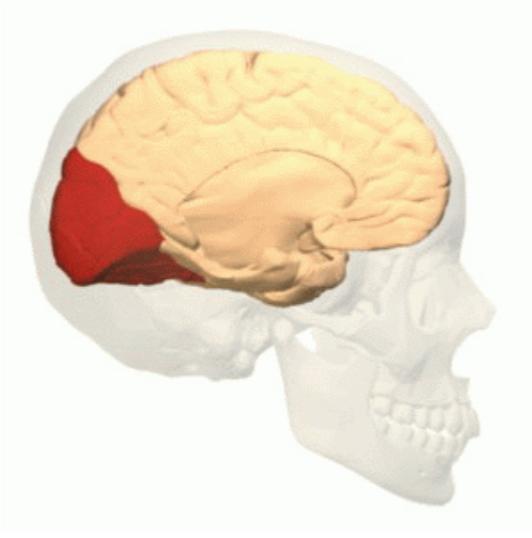
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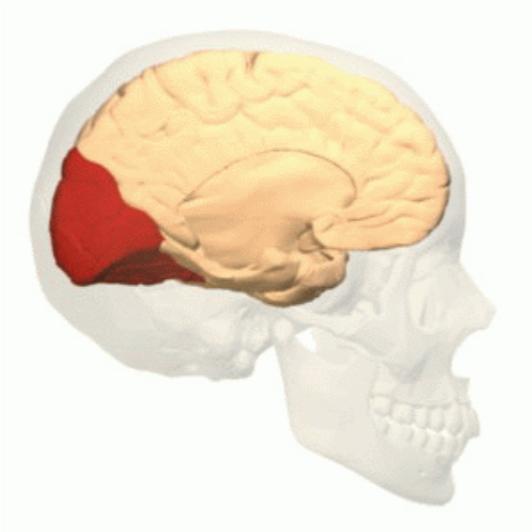
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Layered structure of visual cortex

Lower layers process simple visual features, higher layers -- complex features

Neurons focus on certain areas of visual input

Vision: **hierarchy** of layers



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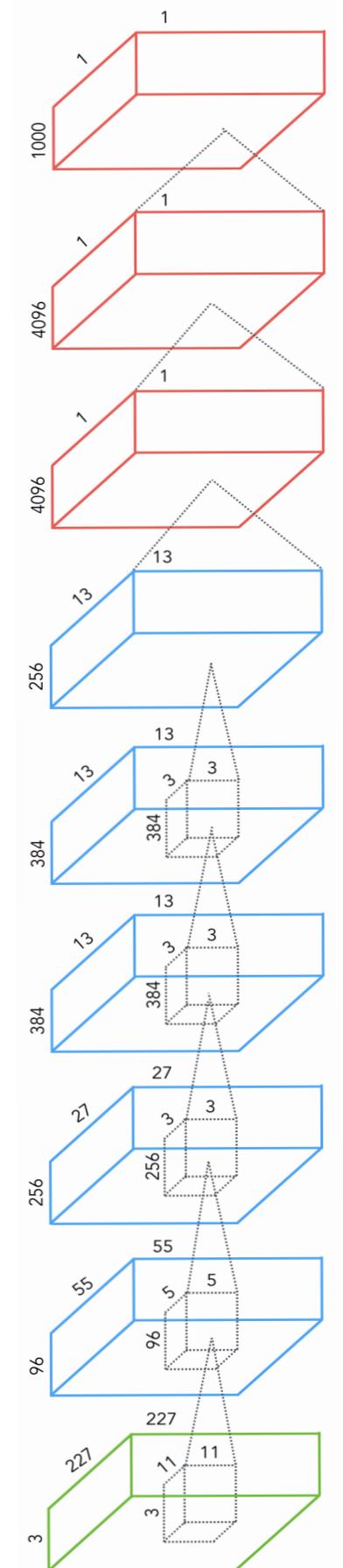


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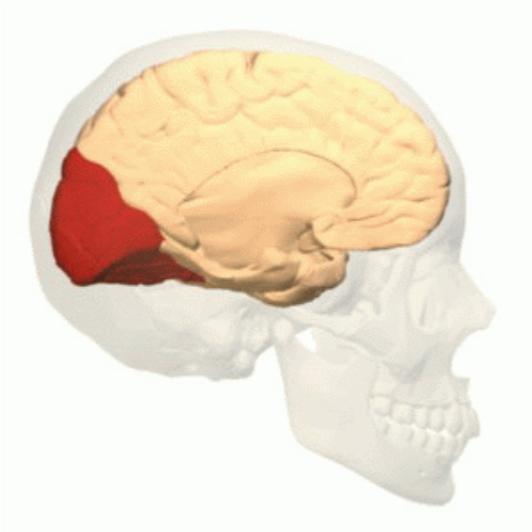
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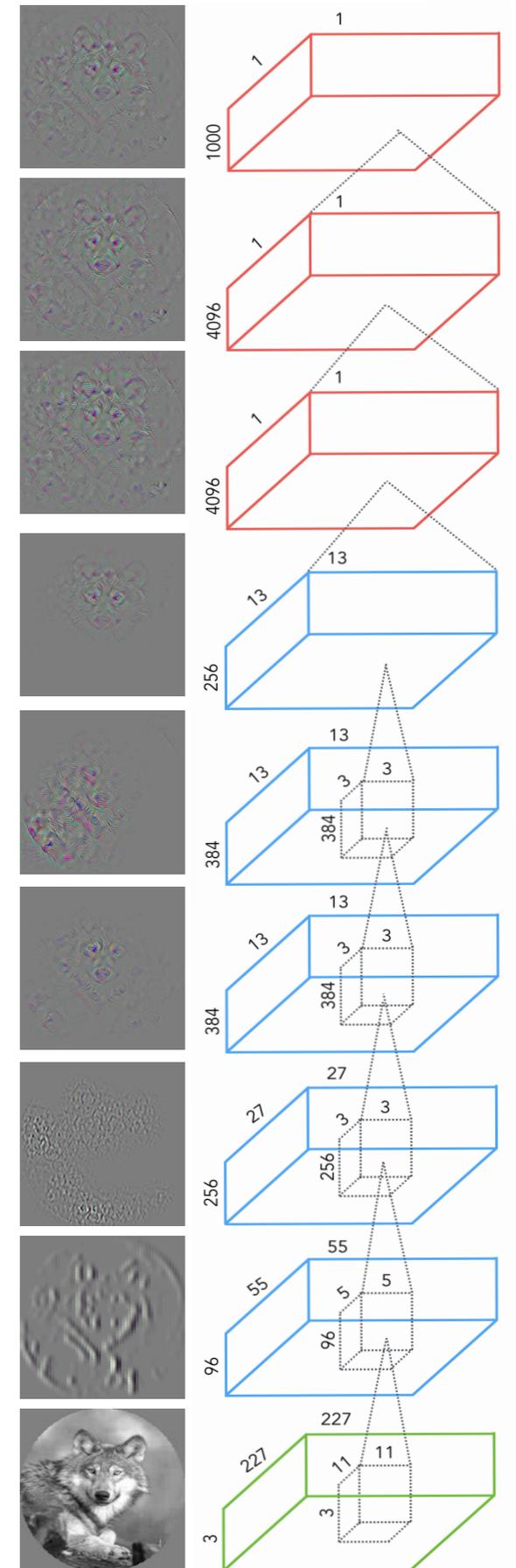


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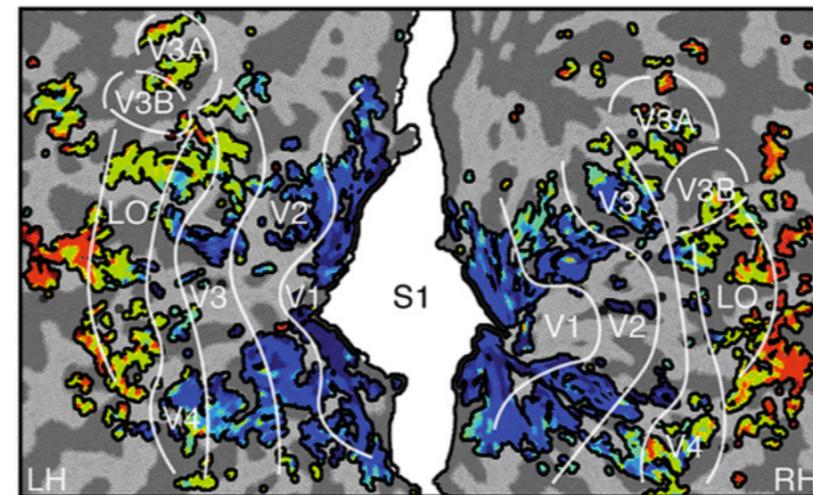
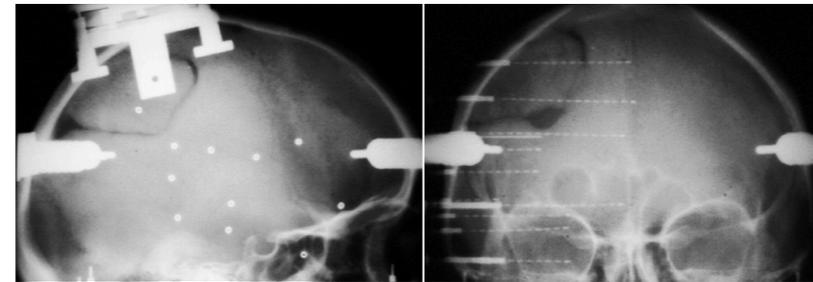
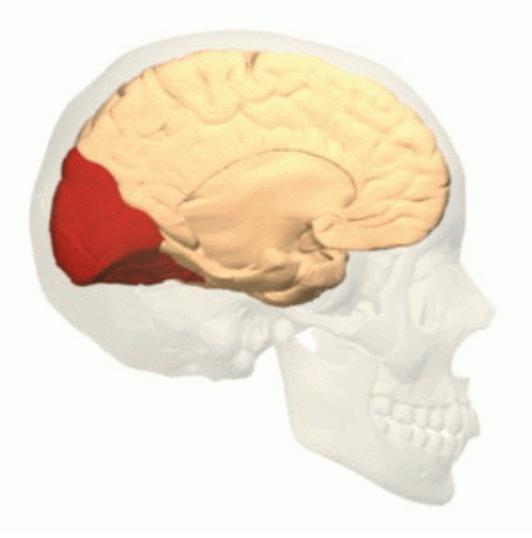
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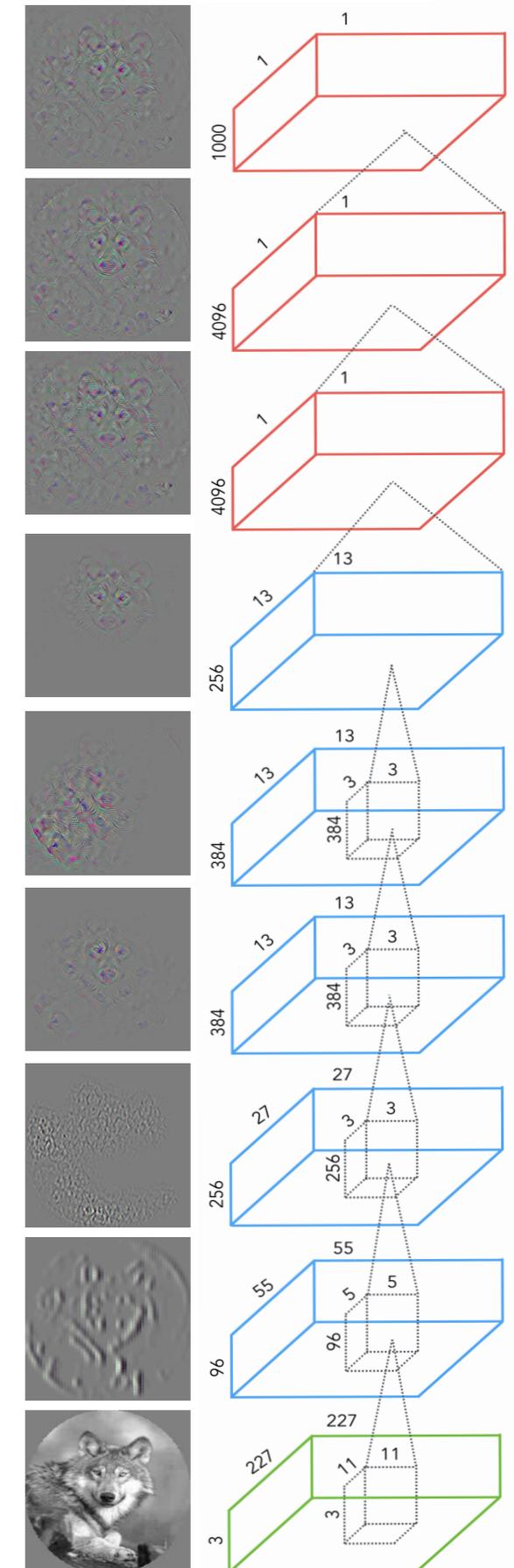
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Model of the world: grid cells

The Nobel Prize in Physiology or Medicine 2014

"for their discoveries of cells that constitute a positioning system in the brain"



O'Keefe

Moser

Moser

Model of the world: grid cells

The Nobel Prize in Physiology or Medicine 2014

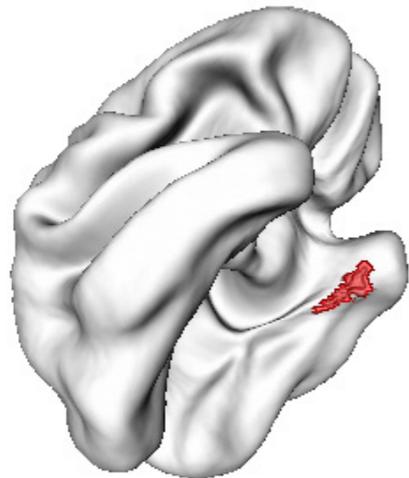
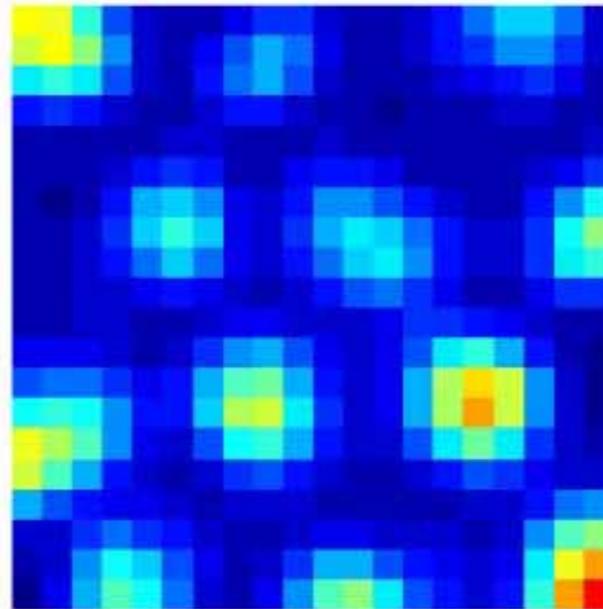
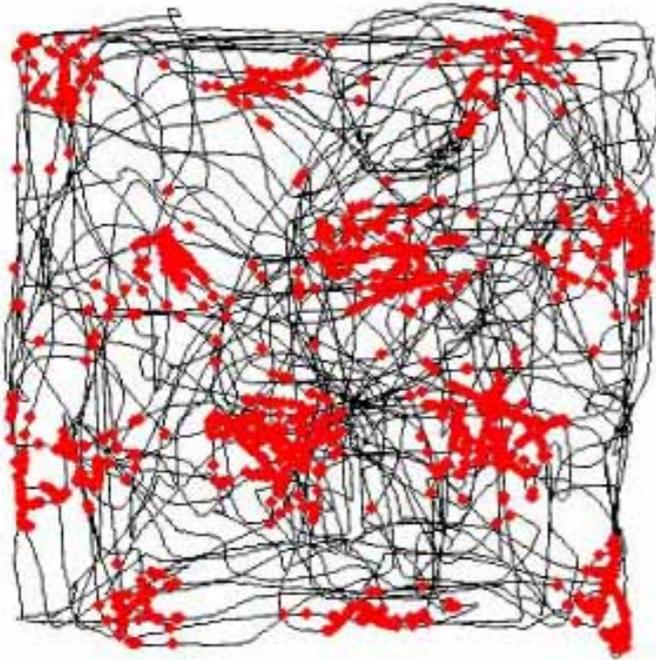
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O'Keefe

Moser

Moser



Entorhinal cortex

Model of the world: grid cells

The Nobel Prize in Physiology or Medicine 2014

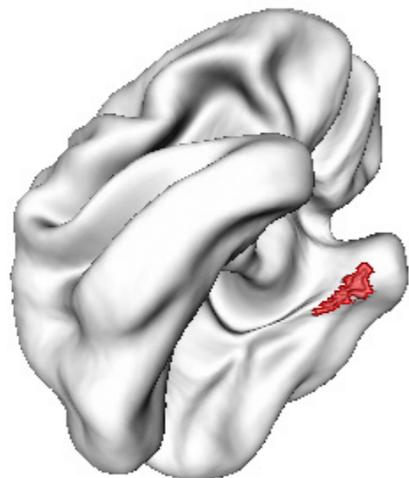
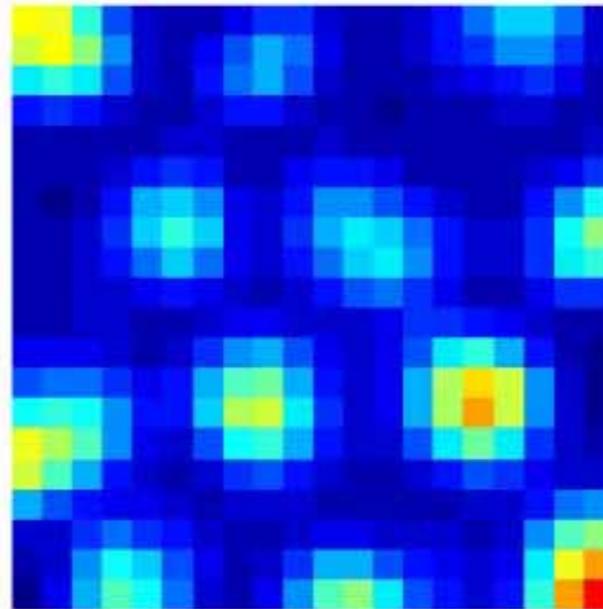
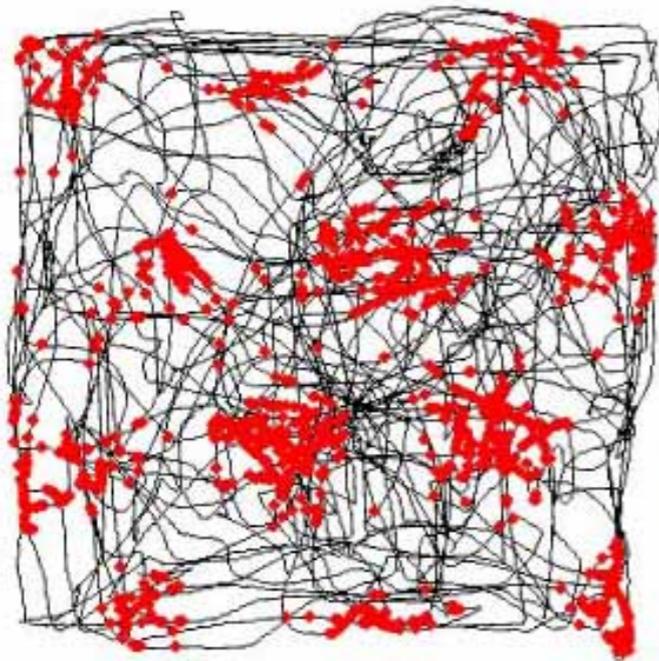
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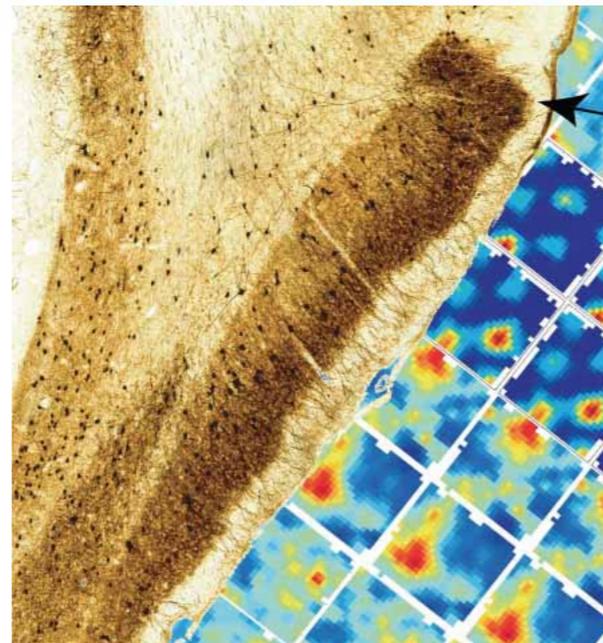
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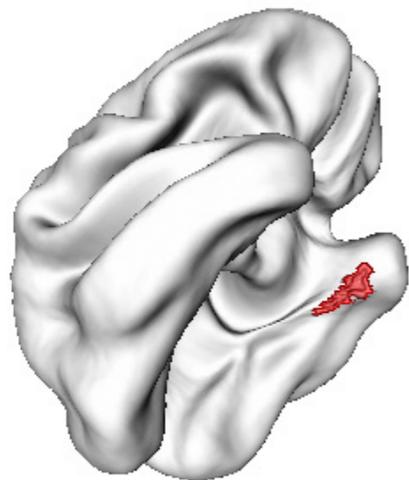
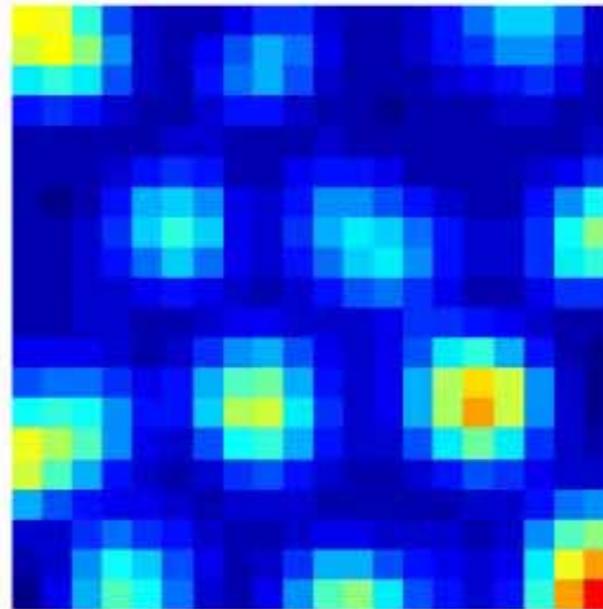
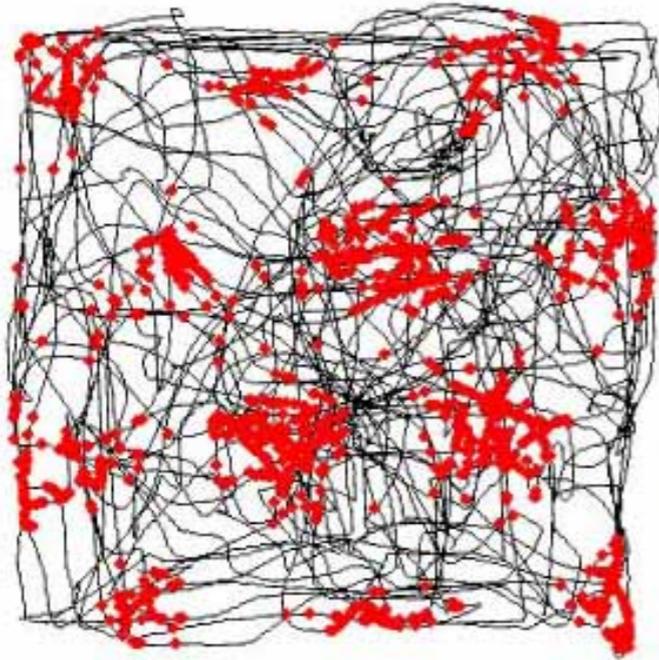
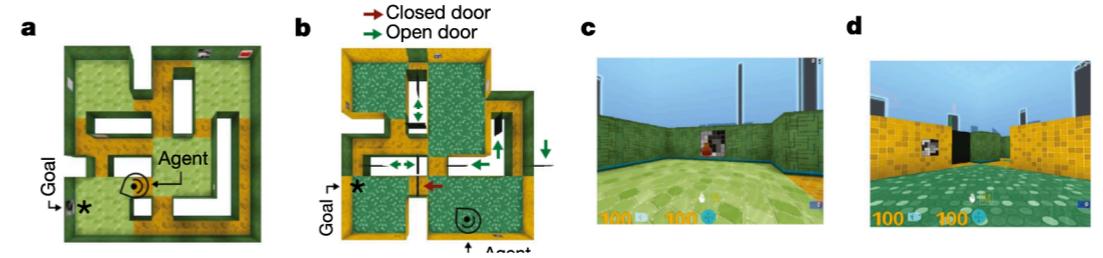
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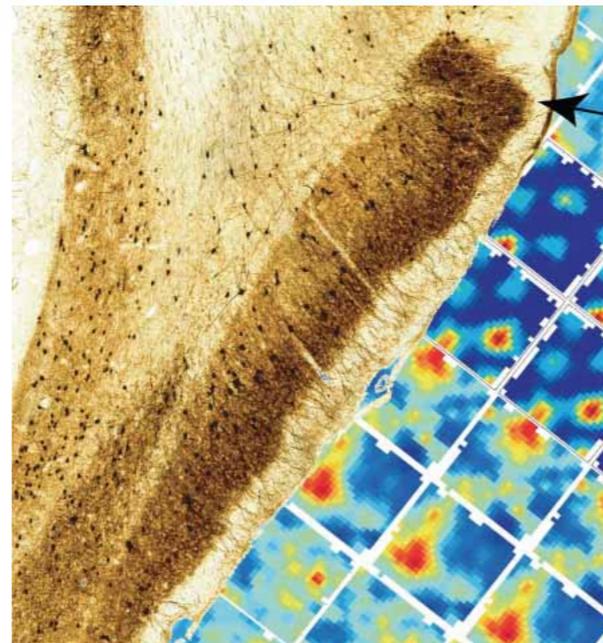
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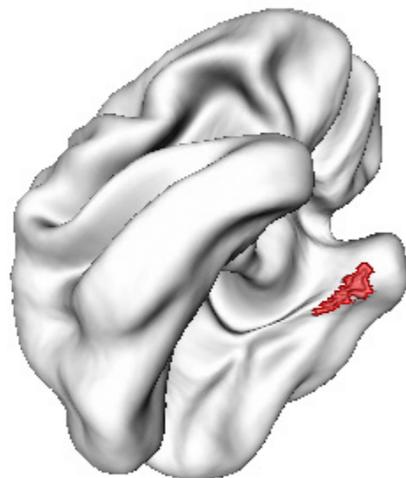
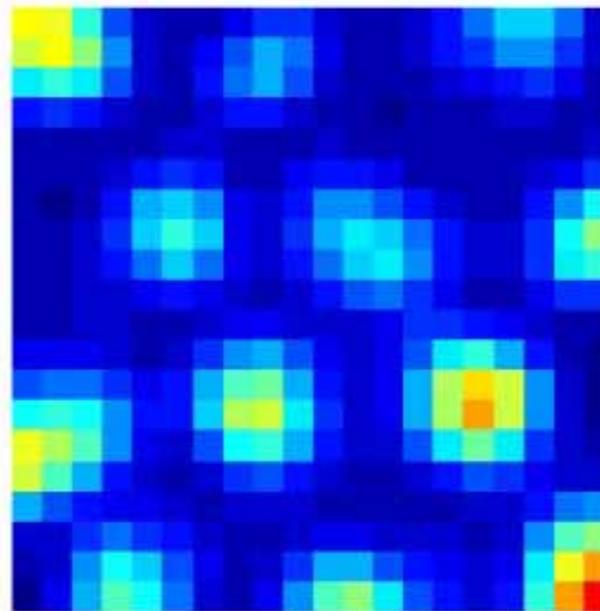
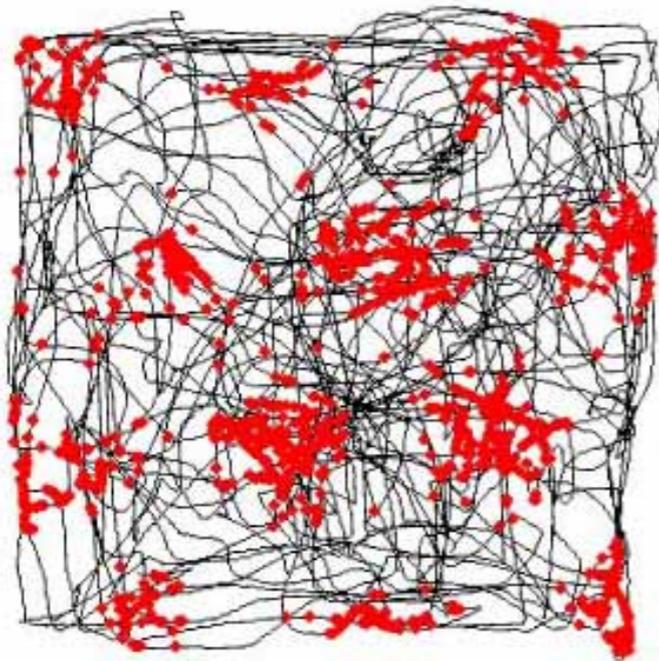
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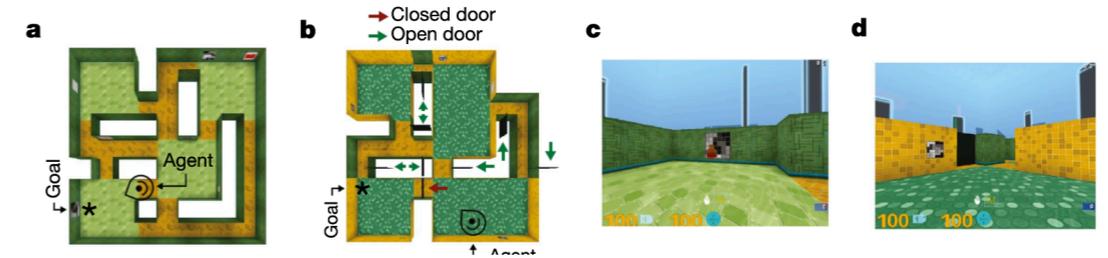
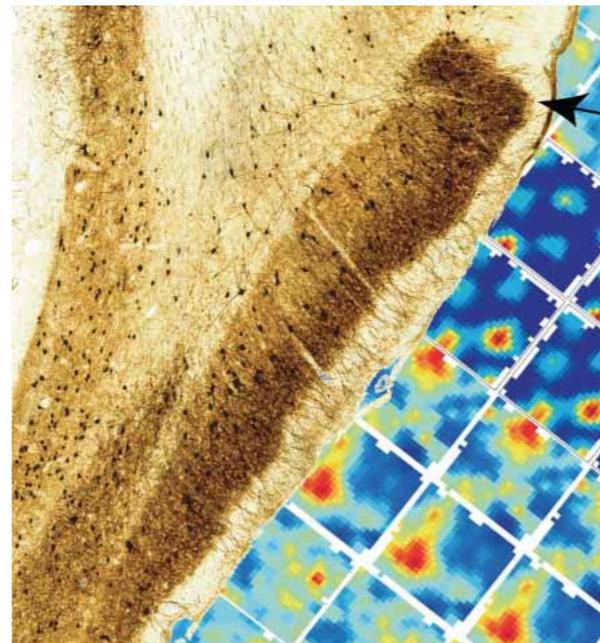
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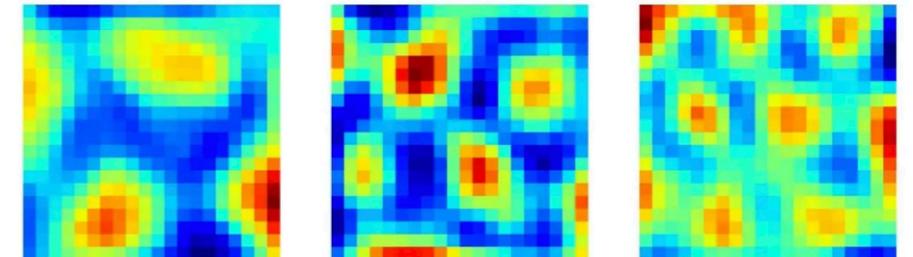


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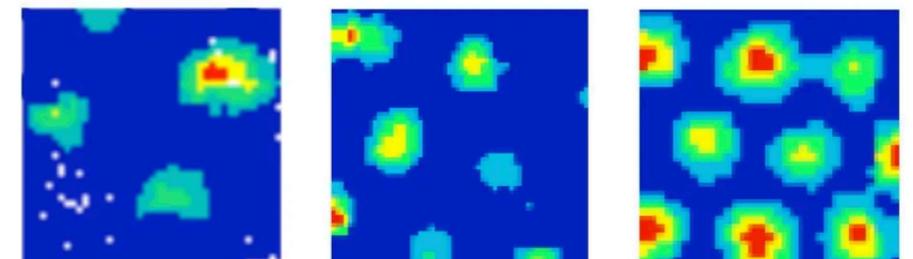


We found that grid-like representations (hereafter grid units) spontaneously emerged within the network – providing a striking convergence with the neural activity patterns observed in foraging mammals, and consistent with the notion that grid cells provide an efficient code for space.

Artificial (Agent)



Biological (Rat)



Our experiments with artificial agents yielded grid-like representations (“grid units”) that were strikingly similar to biological grid cells in foraging mammals.



Model of the world: successor representations

Model-free RL

$$Q^\pi(s, a) = \mathbb{E}_\pi[r_{t+1} + \gamma Q^\pi(s_{t+1}, a_{t+1}) | s_t = s, a_t = a]$$

$$a(s) = \arg \max_a Q_\theta(s, a)$$

+ fast

– inflexible to change

Model of the world: successor representations

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Model-based RL

$$V^*(s) = \max_a \sum_{s'} p(s'|s, a) (r(s_t, a, s') + \gamma V^*(s'))$$

transition reward
probs probs

+ adaptable

– hard to learn

Model of the world: successor representations

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Successor representation for RL

$$V^\pi(s) = \sum_{s'} M(s, s') r(s')$$

discounted future expected
state occupancy state
matrix reward

Why learn the full model when we only care about the chance of getting into a state

Model of the world: successor representations

Model-free RL

$$Q^\pi(s, a) = \mathbb{E}_\pi[r_{t+1} + \gamma Q^\pi(s_{t+1}, a_{t+1}) | s_t = s, a_t = a]$$

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transition probs reward probs

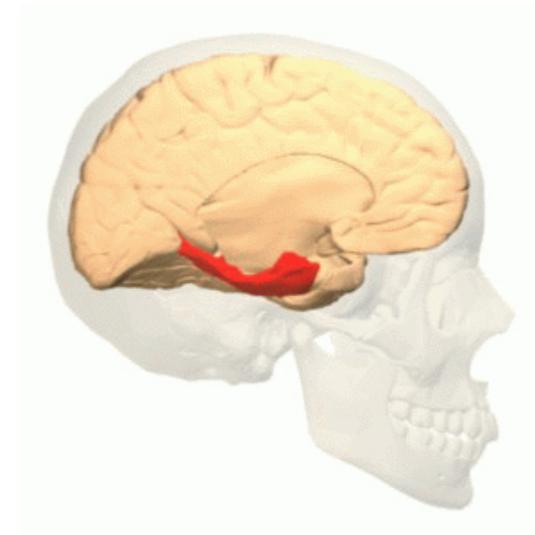
+ adaptable

– hard to learn

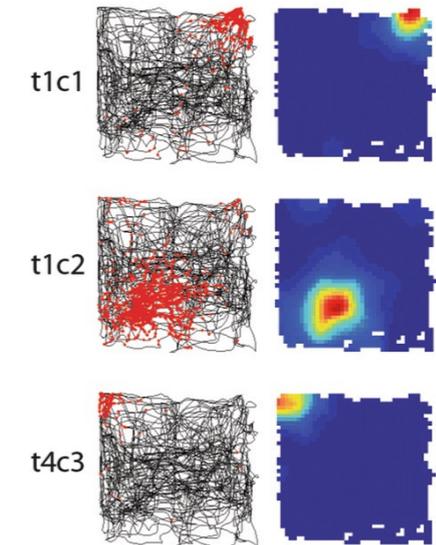
Successor representation for RL

$$V^\pi(s) = \sum_{s'} \underbrace{M(s, s')}_{\text{discounted future state occupancy matrix}} \underbrace{r(s')}_{\text{expected state reward}}$$

Why learn the full model when we only care about the chance of getting into a state



Hippocampus



Place cells

Gaussian distance to the location?

Model of the world: successor representations

Model-free RL

$$Q^\pi(s, a) = \mathbb{E}_\pi[r_{t+1} + \gamma Q^\pi(s_{t+1}, a_{t+1}) | s_t = s, a_t = a]$$

$$a(s) = \arg \max_a Q_\theta(s, a)$$

- + fast
- inflexible to change

Model-based RL

$$V^*(s) = \max_a \sum_{s'} p(s'|s, a) (r(s_t, a, s') + \gamma V^*(s'))$$

- + adaptable
- hard to learn

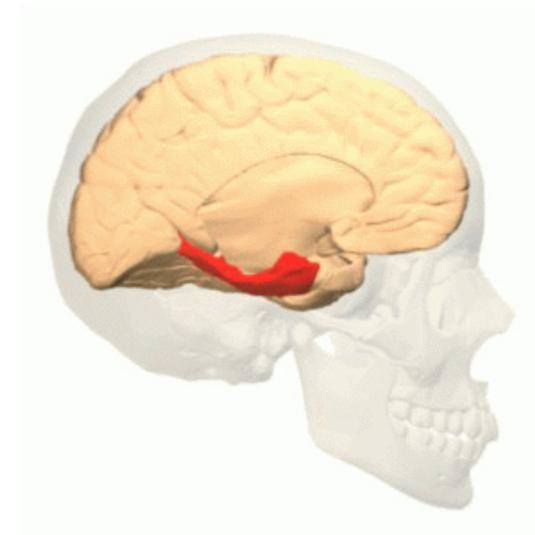
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Successor representation for RL

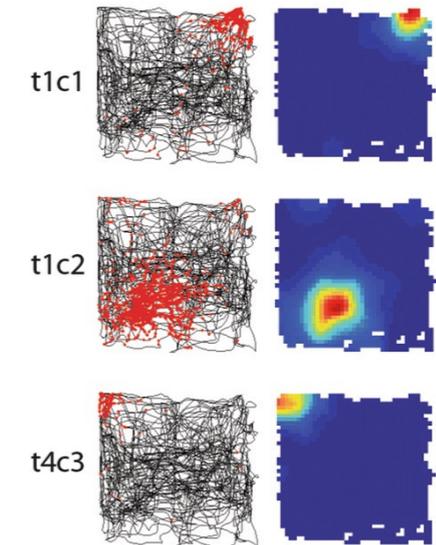
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discounted future state occupancy matrix expected state reward

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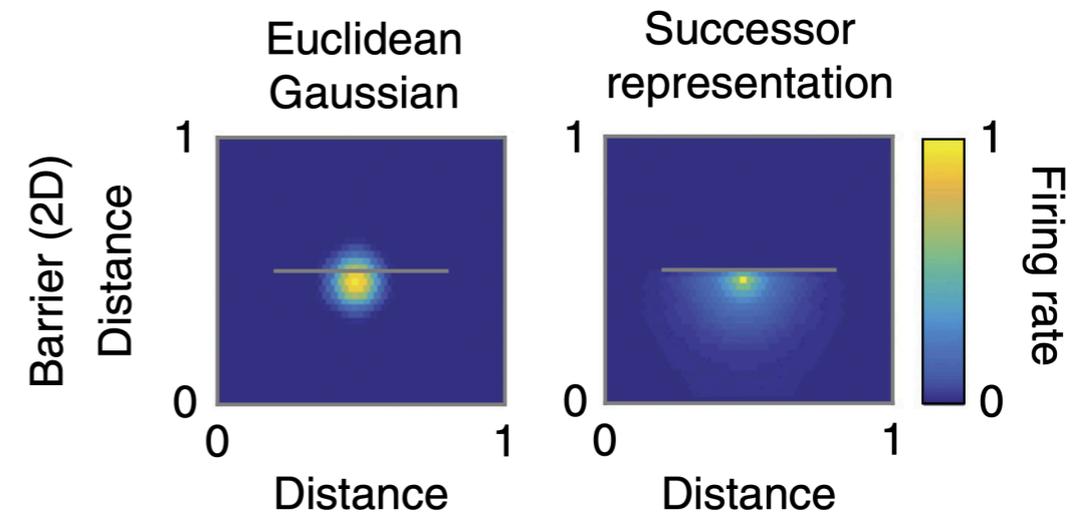


Hippocampus



Place cells

Gaussian distance to the location?



Adding constraints to the environment modifies the shape of the place fields.

SR hypothesis is in agreement with the observation that rewarded locations are represented by a higher number of place cells.

...

Predictive coding

&

Generative Adversarial Networks

Predictive coding

Successor representations

&

MERLIN Architecture

Visual attention

&

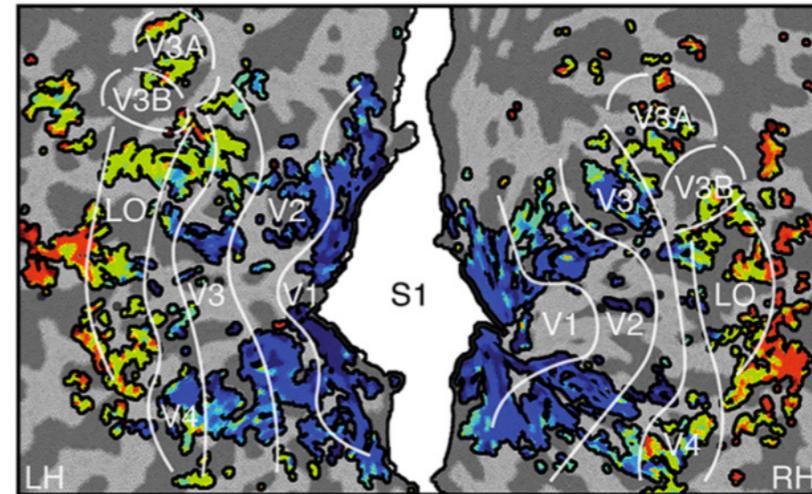
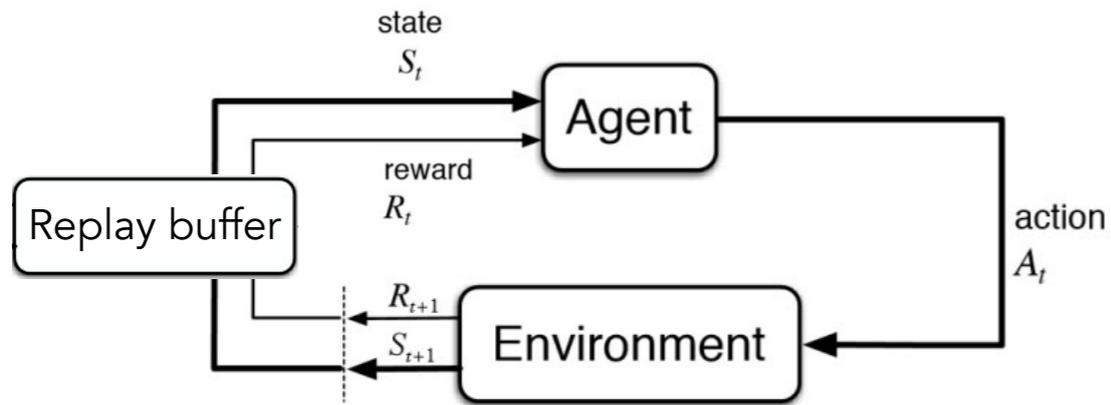
Attention in CNNs

Consolidation of experience

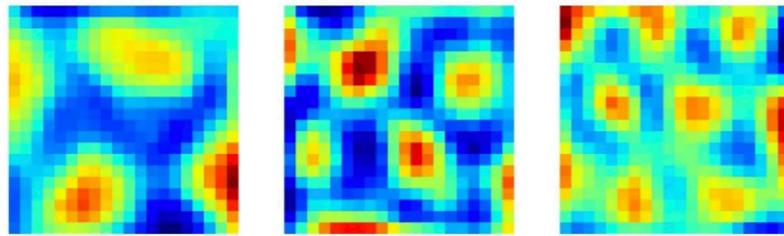
Novel vs. routine circuits

&

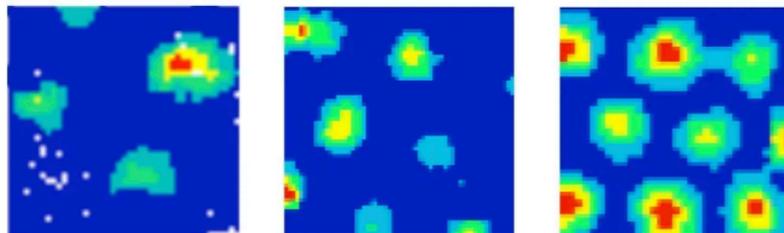
Dual DQN network



Artificial (Agent)

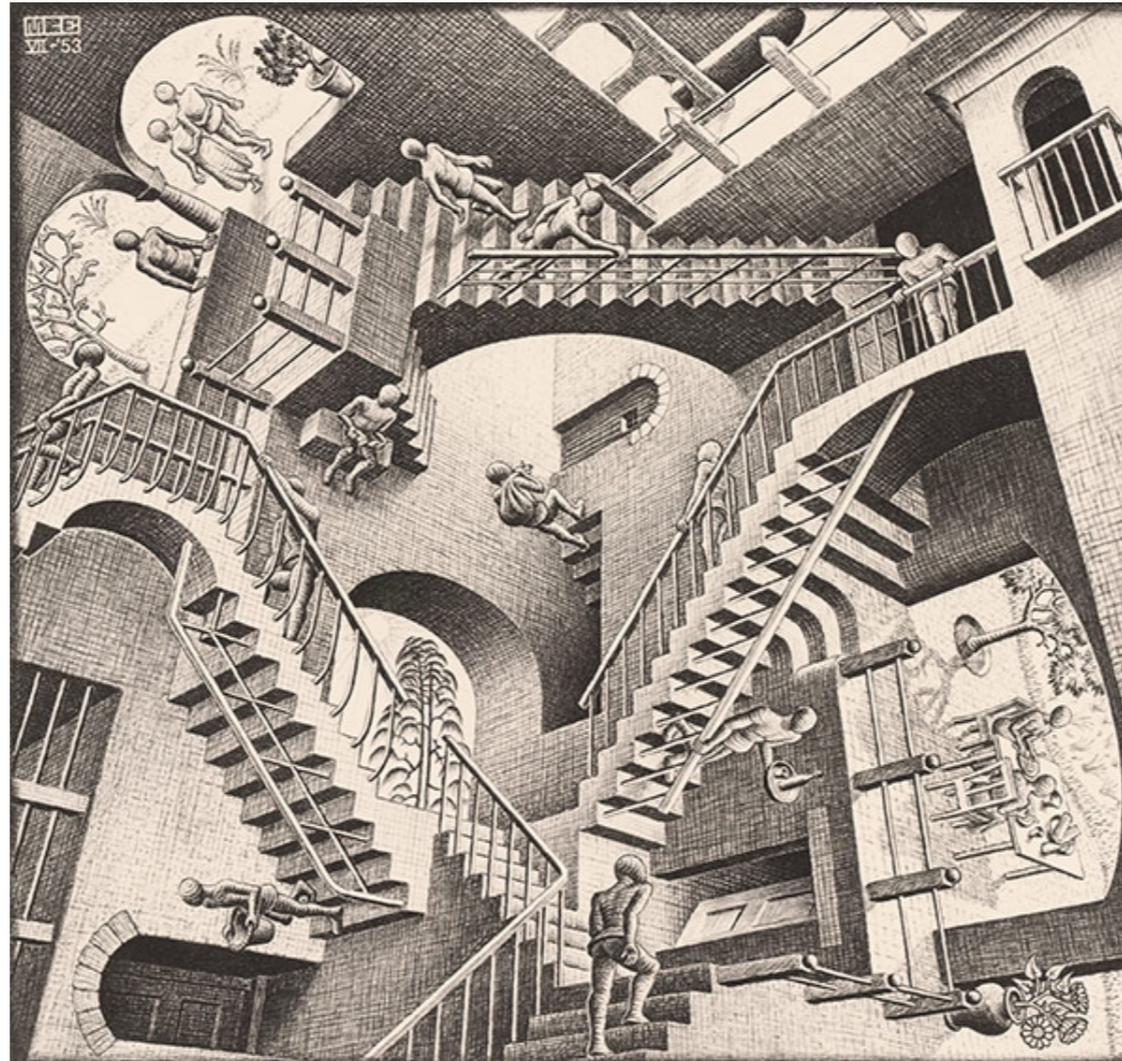


Biological (Rat)



$$V^\pi(s) = \sum_{s'} \underbrace{M(s, s')}_{\substack{\text{discounted future} \\ \text{state occupancy} \\ \text{matrix}}} \underbrace{r(s')}_{\substack{\text{expected} \\ \text{state} \\ \text{reward}}}$$

Curious similarities on the level of algorithm and representation



Goal of computation

Same goal, different strengths... merge!



NeuroChip

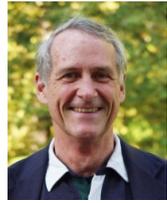
Fetz Lab
University of Washington



Neuralink

Elon Musk
San Francisco, CA

Same goal, different strengths... merge!



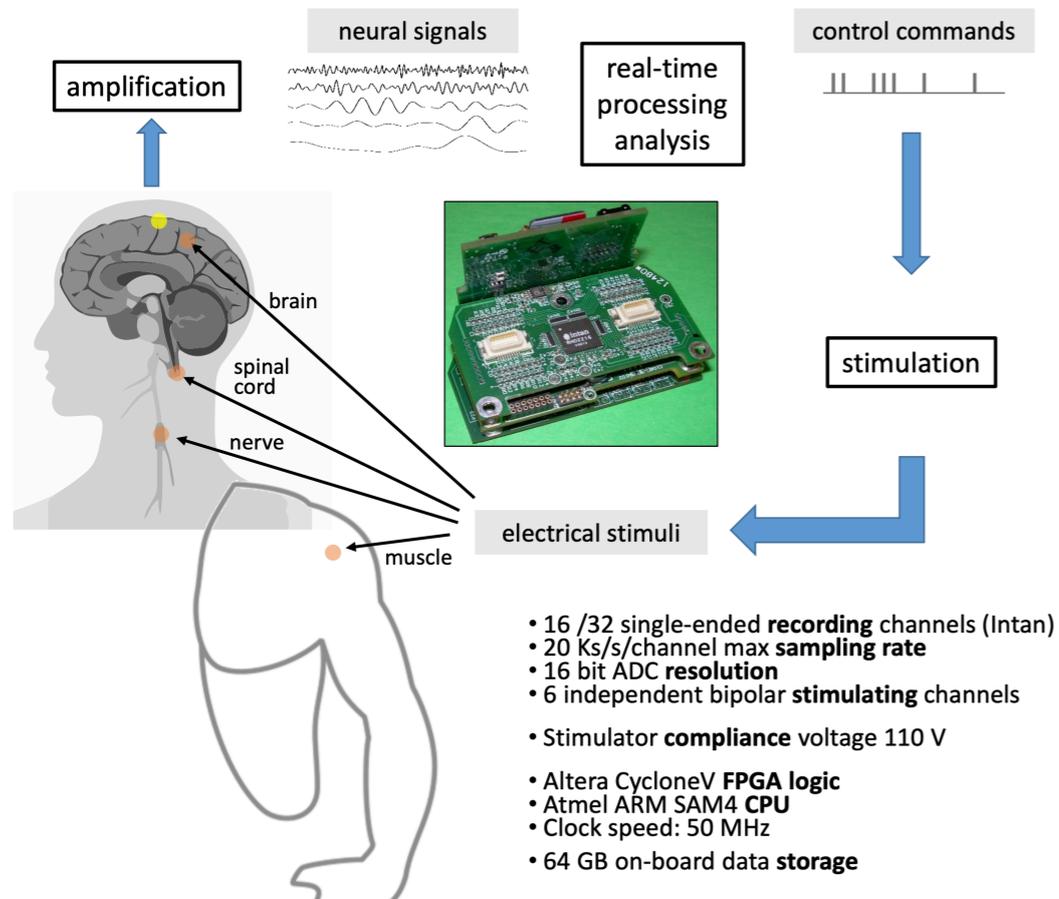
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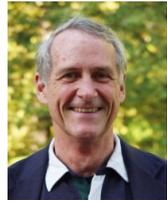


nature
International journal of science

Article | Published: 22 October 2006

Long-term motor cortex plasticity induced by an electronic neural implant

Same goal, different strengths... merge!



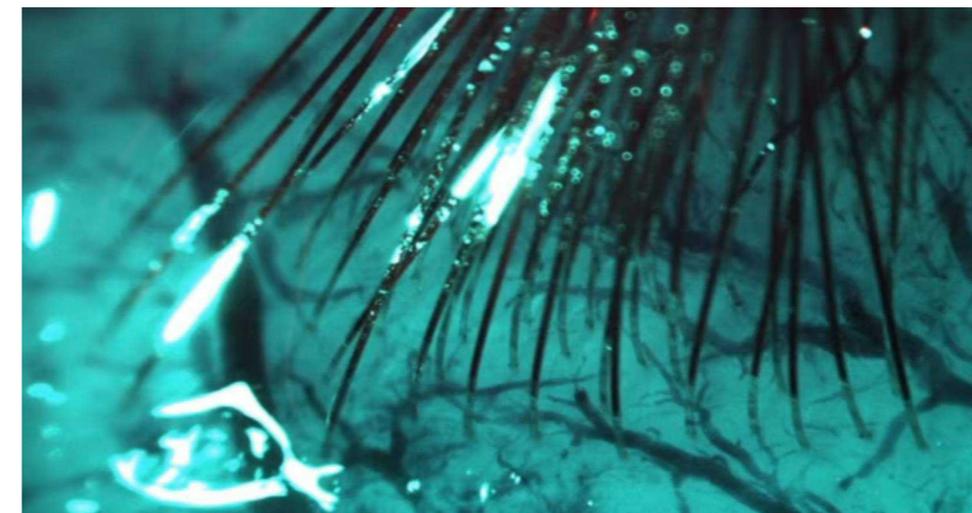
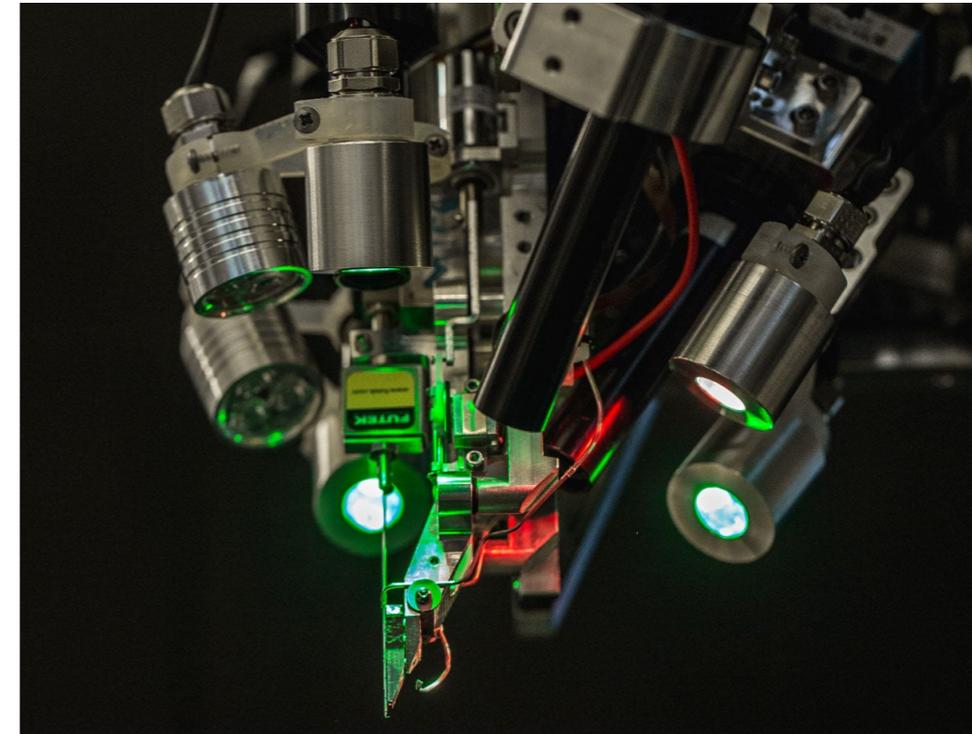
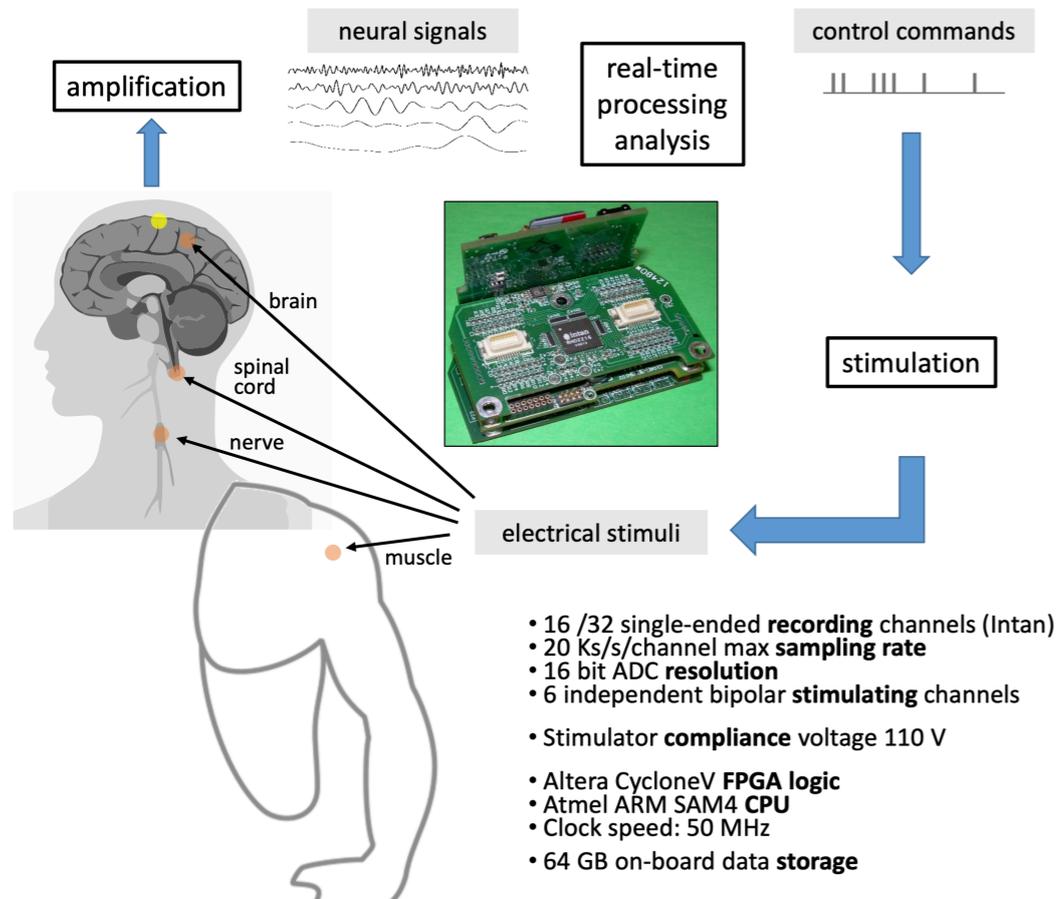
NeuroChip

Fetz Lab
University of Washington



Neuralink

Elon Musk
San Francisco, CA



nature
International journal of science

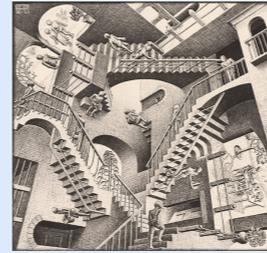
Article | Published: 22 October 2006

Long-term motor cortex plasticity induced by an electronic neural implant

The Brain and the Modern AI

Goal of the computation

What is the purpose of computation?

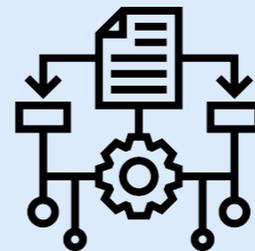


Almost the same

Algorithm and representation

What representations does the system use?

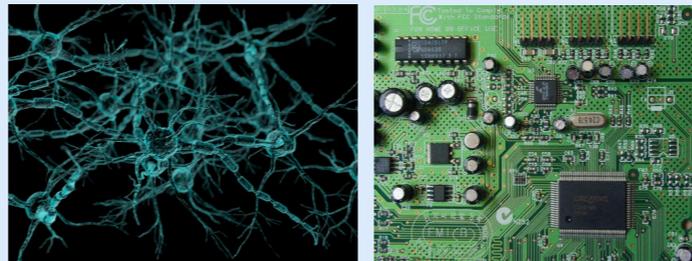
What processes are in use to manipulate representations?



Comparable here and there

Implementation

How is the system physically realized?



Quite different

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Neurotech
Sydney
meetup group

meetup



Neurotech Sydney

📍 Sydney, Australia
👤 51 members · Public group
👤 Organized by Ilya K.

Podcast by
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BRAIN INSPIRED

A podcast where neuroscience and AI converge.

